



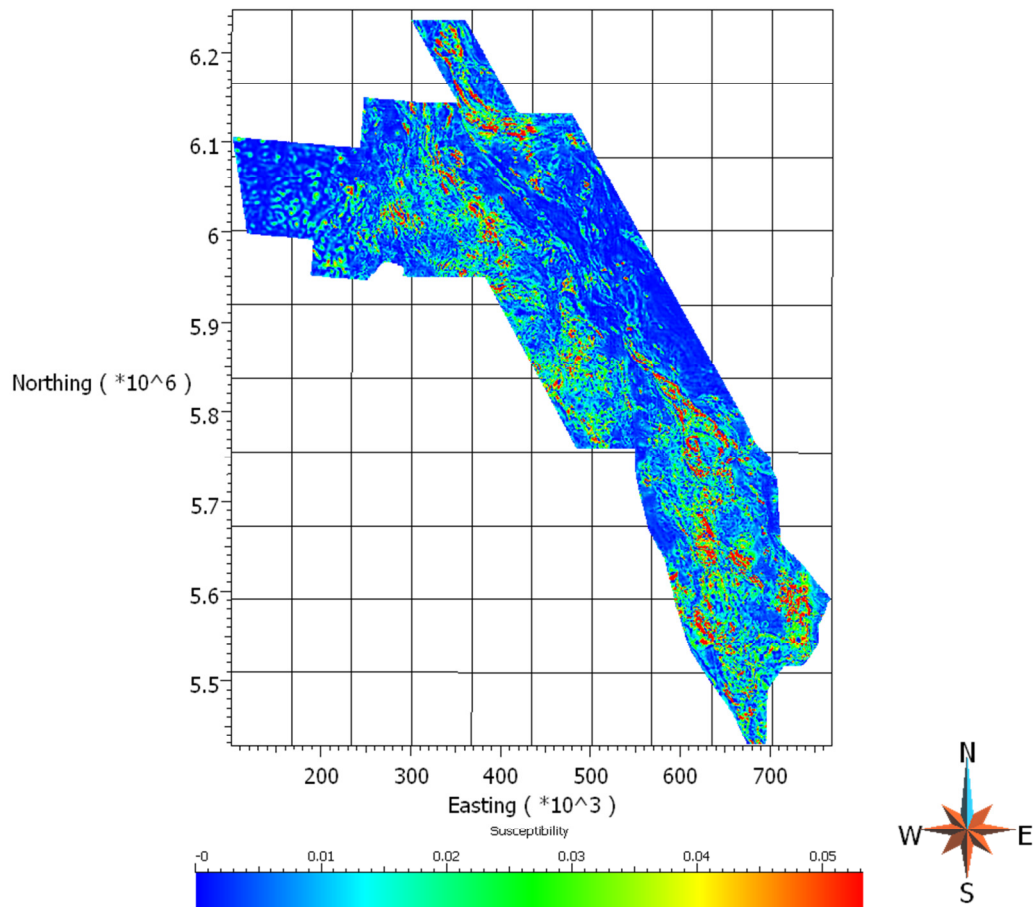
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*...modelling the earth*

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## **Regional 3D inversion modelling of airborne gravity, magnetic, and electromagnetic data, Central BC, Canada.**



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## **Executive Summary**

The Mira Geoscience Advanced Geophysical Interpretation Centre has completed 3D inversion modelling, integration, and visualization of airborne gravity, magnetic, and electromagnetic data for Central BC, Canada including QUEST WEST and integrating it with the Nechako, QUEST, and QUEST South project areas. This was undertaken for Geoscience BC as follow-up analysis of geoscience data. The objective of this work is to provide useful 3D physical property products that can be directly employed in regional exploration to target prospective ground based on different exploration criteria.

This work considers all airborne gravity, magnetic and electromagnetic data available for the project area. The inversions were performed using the UBC-GIF GRAV3D, MAG3D, and EM1DTM, suite of algorithms for the gravity, magnetic, and AEM data respectively. The products are 3D inversion models of density contrast, magnetic susceptibility, and electrical conductivity, and integrated products combining the individual physical property models. In addition, detailed plate modelling of specific EM anomalies in several in-fill survey areas have been modelling using Maxwell discrete plates to provide a better interpretation where the target is less flat-lying in nature.

The gravity and magnetic data were modelled in 3D using several smaller tiles after separation of regional signal. The tiles for the QUEST West and Nechako Basin areas were combined and merged with QUEST and QUEST South models to construct a detailed model over the whole Central BC area.

The conductivity data were inverted for 1D (layered earth) models using a laterally parameterized method and subsequently interpolated in 3D. A late-time, background conductivity map has also been produced for the survey area. An estimate of the depth of penetration has been provided for the AEM conductivity models. The resulting models provide guidance to the regional structure and prospective geology and location of alteration and mineralization.



Final density contrast, magnetic susceptibility, conductivity models have been provided in different formats ready for 3D GIS analysis, interpretation, and integration with geologic, drill-hole, and other geophysical information. The extensive set of digital deliverable products that accompany this report include: physical property cut-off iso-surfaces, observed and predicted data, and the inversion models in several different, commonly used formats. A suite of 3D PDF scenes have been produced to aid in visualization and communication.

The resulting physical property models can be used to guide regional targeting and help design more detailed, follow-up data acquisition. The inclusion of geologic or physical property information in the inversion from maps, drill-holes, and samples was not within the scope of this project, although it is expected that the integration of these data would improve the resulting models, especially at the local scale.

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## 1. Introduction

Geophysical prospecting methods used in exploration provide information about the physical properties of the subsurface. These properties can in turn be interpreted in terms of lithology and/or geological processes. Moreover, the geometric distribution of physical properties can help delineate geological structures and may be used as an aid to determine mineralization and subsequent drilling targets.

The Advanced Geophysical Interpretation Centre at Mira Geoscience has completed 3D density contrast, magnetic susceptibility, and conductivity inversion modelling for Geoscience BC. This was modelled from airborne gravity, airborne total field magnetic, and airborne EM data respectively. The data were collected as part of the Geoscience BC's QUEST West Project; a program of regional geophysical surveys designed to attract the mineral exploration industry to an under-explored region of British Columbia (Geoscience BC QUEST Website). The survey area and data blocks are shown in Figure 1 and include regional surveys and 6 detailed in-fill surveys. The software used for the inversion were the University of British Columbia – Geophysical Inversion facility (UBC-GIF) program suites GRAV3D, MAG3D, and EM1DTM, and Gocad was used for data preparation, inversion management, model integration, visualisation, and interpretation. Maxwell was used to develop the plate models.

Information about the geophysical data used and the data processing is provided in Section 2.

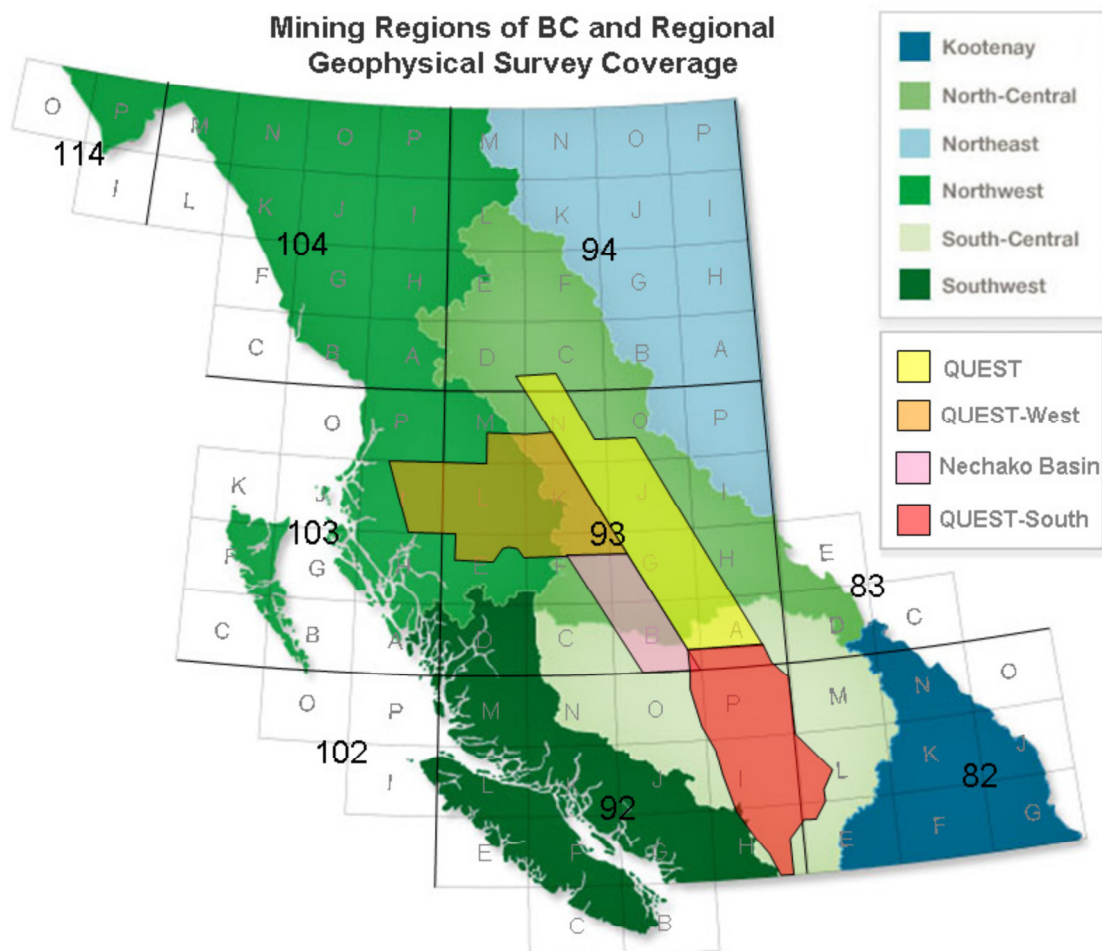
Section 3 details the modelling methods employed, and Section 4 details the modelling results. Regional 3D potential field inversion modelling used a coarse discretization with cells sizes of 2000m x 2000m x 500m in the east, north and vertical directions respectively. This was used for separation of a regional signal prior to detailed local inversion. Detailed local inversions used a more finely discretized 3D mesh with 500m x 500m x 250m cell dimension. The smaller, local inversion cell size is appropriate for the airborne survey data line spacing of 2000 m and 4000 m.

A 3D conductivity model which conforms to topography was constructed by interpolating 1D conductivity models produced from the AEM data at each station along and across survey lines. An estimate of the depth of investigation has been produced for the AEM 1D modelling results.



Topography was used at all stages of the inversion modelling, and the inversions are unconstrained by geologic or physical property information.

The resulting models have been integrated into a Common Earth Model ready for quantitative 3D GIS analysis and integration with additional geoscientific data. Section 5 details the digital modelled, integrated, and visualization deliverables. Conclusions and recommendations are provided in sections 6 and 7, respectively. Several pieces of background and reference material are provided in the appendices.



*Modified after Data Source: Province of BC - GeoBC Data Distribution Service - Mining Regions*

**Figure 1 Map of BC showing the areas covered by Geoscience BC’s regional geophysical surveys as well as the mining regions and NTS map sheets. The Central BC area is defined in this report as comprising the QUEST, QUEST West, QUEST South, and Nechako basin survey areas.**

### **1.1. Geologic Setting**

The primary focus is the Quesnel Terrane which is prospective for copper and gold porphyry deposits, and is locally covered by a thick layer of glacial sediments (Geoscience BC website).

### **1.2. Objectives**

The objective of this modelling work is to provide useful 3D physical property products that can be directly employed in regional exploration to target prospective ground based on different exploration criteria. This is done using physical property-based inversion to determine 3D distributions of density contrast, magnetic susceptibility, and electrical conductivity for an area located in centre of British Columbia, to a depth of 8 km. The models will more easily facilitate geologic interpretation and definition of favorable geology than the data alone, and they can be used in a quantitative manner using 3D GIS analysis. The models can provide important information for determining the depth of overburden and designing appropriate follow-up data acquisition campaigns in favourable areas.

### **1.3. Scope of Work**

The workflow for producing density contrast and magnetic susceptibility models of the Central BC data involves data processing, inversion modelling and finalizing the deliverables. The steps are outlined below:

1. Data quality control, where the data, and survey and instrument parameters are carefully checked for consistency and suspect data are removed. This includes inspection and analysis of geophysical and geodetic data (e.g. analysis of positional and radar altimeter information).
2. Data preparation involving down-sampling or re-gridding, upward-continuation of gravity data, and creation of inversion input files.



3. Regional inversion modelling, which is needed to reduce data, or to provide constraints or background models for local inversions.
4. Detailed inversion modelling at the required resolution using carefully chosen inversion parameters to produce high quality physical property models which, when forward modelled, predict the observed data to an appropriate degree.
5. Layered-earth (1D) inversion of AEM data for all blocks of the QUEST west survey area and the 6 infill areas (Huckleberry, Morrison, Bell, Granisle, Equity Silver, Endako).
6. Plate modelling of discrete AEM anomalies for more steeply dipping features.
7. Construction of final 3D model products through merging and interpolation of detailed models in 3D, and basic analysis and integration of the detailed inversion models.
8. Preparation of deliverables in various formats including Gocad, UBC-GIF, general ASCII, Geosoft grids and 3D PDF.

## **2. Data and Processing**

All data were provided in the NAD83 UTM Zone 10N or 9N Datum and Coordinate System; the modelling was carried out in the same coordinate system. The west part of the QUEST West models have been provided in the native Zone 9N datum, as well as Zone 10N when merged as part of the final Central BC compilation.

### **2.1. Topographic Data**

Topographic data were obtained from the Shuttle Radar Topography Mission (SRTM) database on a 90 m grid. This data was used for the gravity and magnetic modelling. The survey area exhibits some areas of rugged terrain.

#### *2.1.1. Topographic Data Processing*

For both the regional and detailed unconstrained gravity and magnetic inversions the topography data were re-gridded to cover the full mesh. The topographic elevation of a surface cell is equal to that of the data point at the horizontal center of the cell.

### **2.1. Gravity Data**

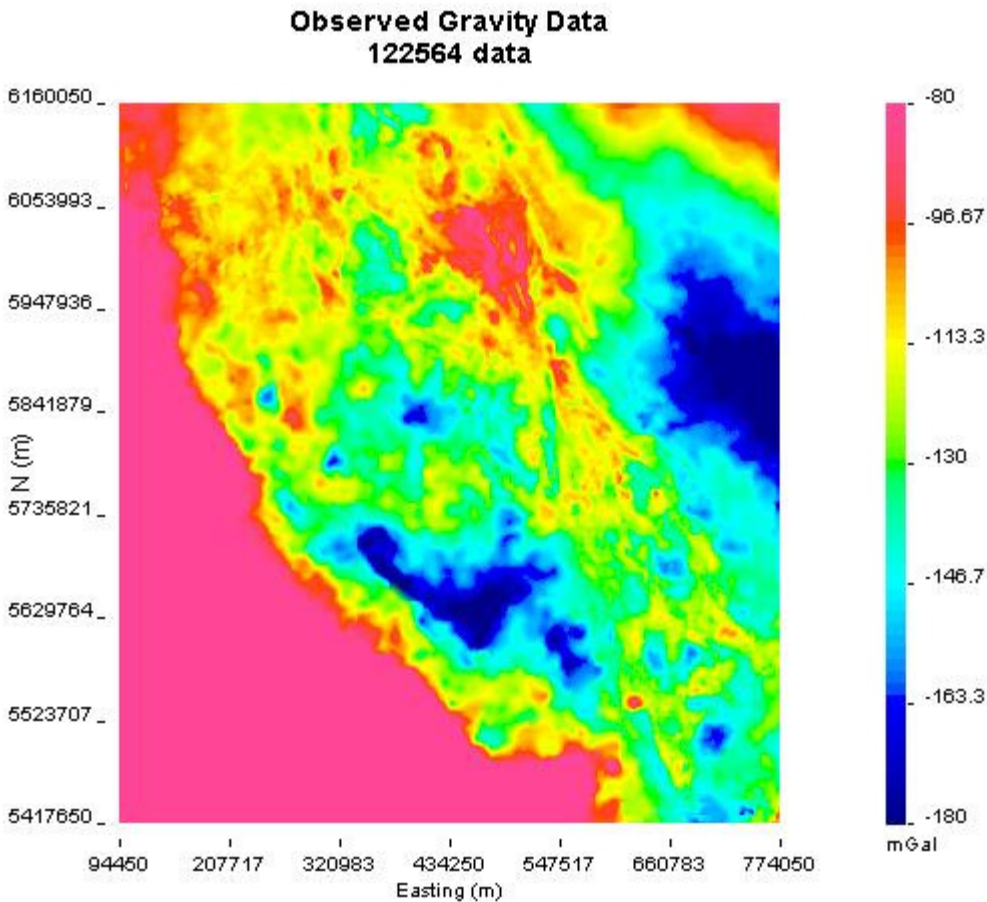
Geoscience BC has provided airborne gravity data with a terrain-correction applied at a density of  $2.67 \text{ g/cm}^3$ , in a gridded format with a 500 m grid size (Figure 4). Airborne gravity (AIRGrav) data were collected by Sander Geophysics with a flight-line spacing of 2000m and notional flight height of 200m. The data were acquired over the QUEST West area for Geoscience BC and collected over the Nechako Basin for the Natural Resources Canada's Mountain Pine Beetle Program. Gravity survey specifications are detailed in the Sanders acquisition report for this survey.

Surface gravity data for the study area, obtained from the GSC and USGS, have also been downloaded from the Canadian repository and USGS databases (Hildenbrand, 2002). These datasets were used to complete the airborne gravity in order to obtain full coverage of the study area for the regional inversion prior to regional removal.

### *2.1.1. Gravity Data Processing*

For regional inversion, the GSC surface gravity data were upward continued 250 m above topography to reduce cell effects from the discretization of the model. These upward continued data were merged with the airborne gravity to obtain full coverage of QUEST, QUEST-West, Nechako, and QUEST-South projects areas from 94450 to 774050 m Easting and 5417650 to 6160050 m Northing. The gravity data were re-gridded at 2000 m sample intervals for the regional inversions. A standard deviation of 4 mGal was assigned to the data. This value is ~ 2% of the total range of terrain corrected data.

For the detailed inversions, the GSC surface gravity data were upward continued 125 m above topography and the gravity data were re-gridded at 500 m sample intervals.



**Figure 2. Terrain-corrected gravity data prepared for regional inversion modelling.**

## 2.2. Magnetic Data

Magnetic data downloaded from the GSC Canadian repository databases and USGS magnetic data (USGS Open-File Report 2002–361) have been used for magnetic inversion.

The GSC magnetic data were collected from 1947 to the present and consist of 500 surveys generally with a line spacing of 800 m and an altitude of 305 m above the ground (available from the Geophysical Data Repository at Natural Resources Canada).

The data sources were combined to form the final Total Magnetic Intensity magnetic data coverage for the inversions.

All supplied data were imported into Gocad. They were checked for quality and consistency, processed and edited if necessary, re-sampled, and converted to a format suitable for unconstrained 3D gravity and magnetic inversions.

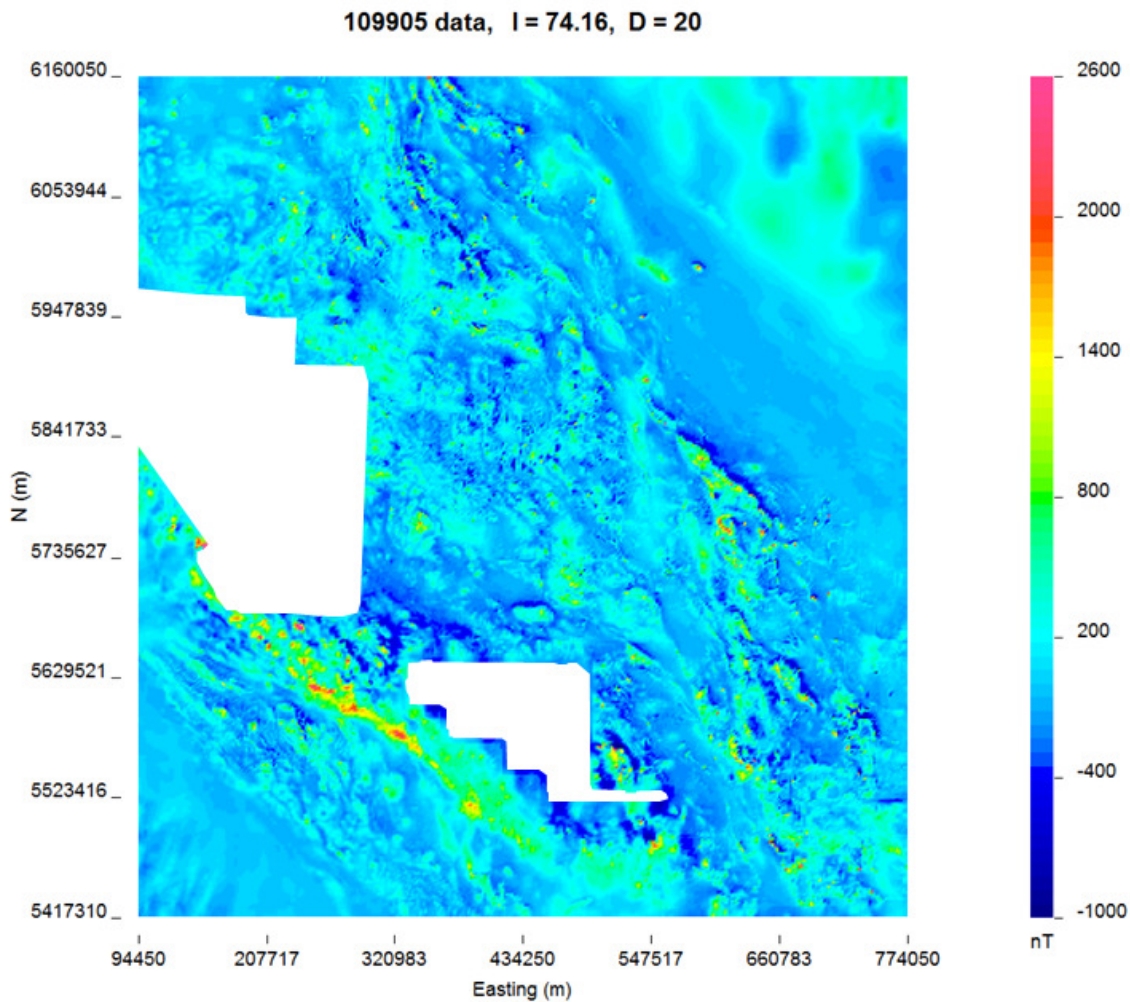
A standard deviation is assigned to the data for inversion modelling purposes. The standard deviation represents an estimate of all possible sources of data uncertainty including: sensor sensitivity and noise, GPS location uncertainty, modelling uncertainties (topographic representation in the model or small sources that cannot be accounted for in the discretization). The assigned value is a starting estimate and the actual level of data misfit is determined during inversion.

#### *2.2.1. Magnetic Data Processing*

Data were examined and edited for bad data points. Data for which there was no elevation information in the data base were discarded. The USGS data were merged with the GSC magnetic data to obtain full coverage of QUEST, QUEST-West and QUEST-South projects areas from 94450 to 774050 Easting and 5417650 to 6160050 Northing.

The Canadian Geomagnetic Reference Field (CGRF) value was removed from the data. A starting standard deviation of 100 nT was assigned to the data. The data were prepared in UBC ASCII data format.

The total magnetic intensity (TMI) data were re-gridded at 2000 m intervals for the regional inversion, and at 500 m for the detailed inversions. The inducing field parameters used were those appropriate for the centre of the QUEST, QUEST-West and QUEST-South survey areas (longitude 123°13'30 E and latitude 54°17'39 N) and a date halfway through the acquisition of the magnetic data. The inducing field does not vary more than 1.5 degrees throughout the whole expanse of the survey area so using a single direction for the inducing field was felt to be a reasonable assumption. The magnetic data, as prepared for the regional inversions, are presented in Figure 3.



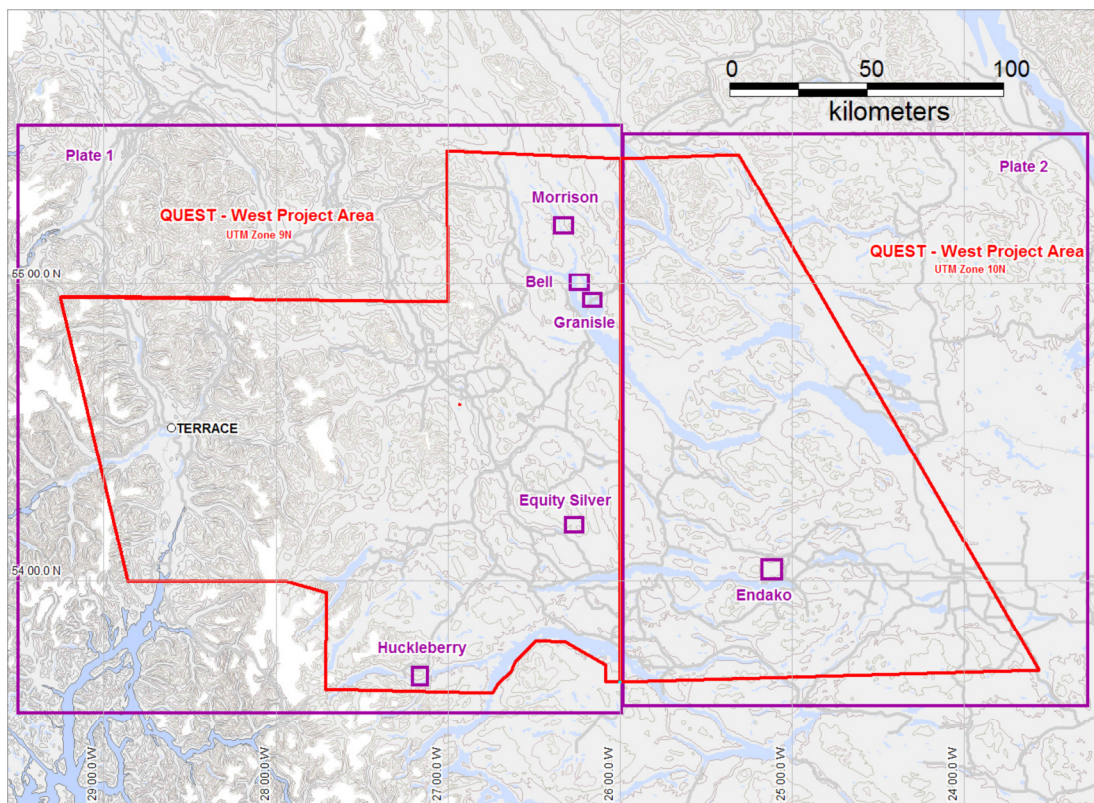
**Figure 3: Total Field Magnetic Intensity data prepared for regional inversion modelling. The CGRF has been removed.**

### 2.3. Airborne EM data

Helicopter-borne AeroTEM data were collected by Aeroquest Ltd. concurrently with the airborne magnetic data acquisition and have the same data coverage. The AeroTEM III electromagnetic system was used with a high-sensitivity caesium vapour magnetometer.



The total survey coverage is 13,219.1 line-km. Line spacing for the main survey was 4000 m with no tie-lines. Lines were flown East-West and the main survey split into 9 parts (A1, A2, B1, B2, C1, C2, C3, D, F) and 6 in-fill areas with 200 m line-spacing and tie lines present (Bell, Endako, Equity, Granisle, Huckleberry). The last 15 of the 33 data channels (the off-times) were used for the inversion. The airborne electromagnetic data are assumed to have had adequate quality control procedures applied although some bad data were removed during additional quality control processing.



**Figure 4: AeroTEM project survey area (from the Aeroquest Limited - Report on a Helicopter-Borne AeroTEM System Electromagnetic & Magnetic Survey - Job # 08130)**

The AeroTEM survey specifications are detailed in Appendix 2, and more information regarding the survey can be found in the Aeroquest survey acquisition report.

### 2.3.1. *AEM Data Processing*

Due to the high rate of data sampling with airborne EM systems, the data were down-sampled to an average station spacing of 16m. This along-line sampling rate is less than the nominal flight height (~30m) and thus is small compared to the resolution of the airborne data. The airborne electromagnetic data are assumed to have had adequate quality control procedures applied. It is noted however, that the surveyed area contains a railway line as well as pipelines and high voltage electrical transmission lines. The data were filtered to minimize effects associated with culture by applying a frequency cut-off filter. The cut-off was derived from the power line monitor data, which measures the 60 Hz EM frequency during the flight. The values from the monitor data are uncalibrated and provide relative information about the intensity of the power line noise. When a value is close to zero, it means there was no 60 Hz EM field close to the EM receiver. High values on the other hand identified data locations where power noise was problematic and data were correspondingly discarded. Some data were also omitted from the final inversions because of system errors. In addition, decays with significant negative data were removed.

Noise and errors in the data can be caused by a number of issues. The most common are equipment and system errors, operator errors, GPS location errors, and modelling errors. When inverting the data it is important to assign uncertainties to the data to account for these errors. We assume that the data errors are Gaussian and independent and have a standard deviation equal to a percentage of the magnitude of the datum plus a floor. The percentage value is needed to account for errors on data with a large dynamic range. The floor value is needed when data are small compared to the noise. The uncertainties are assigned as standard deviations for each channel.

### **3. Geophysical Inversion Modelling**

#### **3.1. Potential Field Modelling**

##### *3.1.1. Gravity Modelling*

Terrain-corrected gravity data are inverted to recover a 3D distribution of density contrast. The contrast is referenced to the density at which the terrain correction is applied ( $2.67 \text{ g/cm}^3$ ). Topography is included in the inversion. The models are produced using the UBC-GIF inversion GRAV3D code (Appendix 3).

##### *3.1.2. Magnetic Modelling*

Total Field Magnetic data are inverted for a 3D susceptibility model of the earth using the UBC-GIF MAG3D inversion code (Appendix 3). The correct inducing field parameters are needed as well as the data. The assumption has been made that no self-demagnetization or remanent magnetization effects are present (see Appendix 5 for further discussion). Topography is included in the inversions.

##### *3.1.3. Model Discretization*

Geophysical inversion modelling has been performed using a parameterization of the earth which employs many finely discretized cells or layers, each of which has a constant physical property value. The discretization is in the form of cuboid cells for the 3D gravity and magnetic inversions, and is commonly referred to as a mesh. The mesh parameters are based on the survey and system parameters, and are made small enough to reduce modelling errors due to discretization (such as the topographic representation) and are also small enough so that they do not introduce additional regularization in the inverse problem. Discretization parameters are tabulated in Appendix 6 for both the regional and detailed 3D gravity and magnetic inversions.

The 3D models have a core mesh of regularly sized cells corresponding to the lateral extents of the data. Padding cells of increasing dimensions extending east, west, north, south, and vertically down complete the volume used in the inversion. The padding cells help accommodate signal

(often regional) that cannot easily be accounted for in the core mesh. Padding cells are removed for deliverable model products.

Both the gravity and magnetic inversions use the same 3D mesh, so direct evaluation can be made between the density contrast and magnetic susceptibility models. This representation of different physical property models (and different earth properties in general) allows quantitative 3D-GIS analysis of the modelling results.

#### *3.1.4. Separation of Regional Potential Field Signal*

A method for separating regional and residual gravity and magnetic fields using an inversion algorithm was presented in Li and Oldenburg (1998). The separation is achieved first by inverting the observed gravity or magnetic data from a large area to construct a regional physical property distribution (usually with a more coarsely discretized model). The local volume of investigation is removed from the regional model (model cell values in that volume are set to 0) and the gravity or magnetic fields are calculated and then used as the regional field. The residual data are obtained by simple subtraction of the regional field from the original data.

These residual data reflect the response from local and shallower geology that are often dominated by stronger regional sources, and they can be subsequently inverted on the local volume of interest (usually with a more detailed model discretization). The residual data may also be useful for qualitative interpretation of geology within the volume of interest.

This modelling-based approach to regional signal removal provides a robust result that is consistent with the modelling objectives. The modelling workflow is outlined below:

1. *Regional Inversion*: Invert the entire dataset using a coarse mesh to produce a regional model.
2. *Regional Response*: Define a local volume of interest. Set the physical property value to zero inside this volume and forward model to obtain the regional response.
3. *Regional Removal*: Calculate a residual by subtracting the regional response from the original data.

4. *Detailed, local Inversion:* Invert the residual data using a refined mesh over the local volume of interest.

The regional separation method can be employed to invert very large areas where the number of model parameters at the desired detail of discretization would make the inversion of the entire dataset prohibitively slow. By calculating a regional response for different local volumes of interest (tiles), a separate local inversion can be performed on each residual dataset. A detailed model of the entire area can then be simply constructed by merging the local inversion models.

### 3.2. Airborne EM Modelling

The AEM inversions were performed using the 1D electromagnetic inversion program EM1DTM, developed at the University of British Columbia – Geophysical Inversion facility (UBC-GIF). This program is a versatile inversion code capable of inverting 3 component data from magnetic sources. The algorithm is designed to invert for a model with many more model unknowns than input data so that the character of the recovered model is determined by a model objective function and not solely by the goal of fitting the data.

The input to the algorithm is the time-domain EM data for each channel, assigned data uncertainties, transmitter and receiver positions and altitude, transmitter waveform, system information, and model and inversion parameters (e.g. layer thicknesses, background conductivity, and level of desired data misfit). The outputs are: a finely discretized 1D conductivity model for each sounding, the predicted data, and a number of measures which can be used to evaluate the quality of the inversion results. The recovered conductivity is smoothly varying in depth while at the same time it is minimally different from the prescribed reference conductivity. It predicts the observed data to an appropriate degree that is justified by the assigned errors in the data. The algorithm is capable of producing L2 (smooth) and L1 (blocky) model results but the L2 option is most commonly used. This means that sharp boundaries will appear somewhat smoothed in the final model although increased structure can be infused by use

of a layered reference model. Appendix 3 provides more detailed information on the EM inversion software.

Each sounding is inverted individually. The 1D conductivity models are presented side-by-side along line and also interpolated between lines to create approximate 3D conductivity models of the earth.

### 3.2.1. *Laterally Parameterized AEM Inversions*

There are many input data and parameters for the 1D EM inversions and it is often difficult to optimize these parameters for every sounding in a large survey. When the parameters are not appropriate, artifacts can appear in the resulting models that can be misleading to the interpreter.

Two of the parameter selection issues faced are explained below:

1. Due to the large area covered by AEM surveys, the host geology, in which anomalous zones are being sought, will often vary considerably. In terms of the EM survey this means the background conductivity will change over the survey area. For the inversions being performed on these data, the reference conductivity model should be varied accordingly.

The EM inversion code has functionality for calculating the best-fitting conductivity halfspace for the data at each sounding along a line. Often this value is a reasonable representation of the bulk conductivity at the sounding location. The best fitting halfspace can be used as a starting and reference model. However, if the conductivity varies greatly with depth, or if the conductivity has large changes in the lateral direction (as would be the case for a contact zone) then the best fitting halfspace is not an adequate representation of the local geology. A more robust procedure is required to compute a background reference model for each station.

2. The level of data misfit is often hard to determine for each sounding along a line because noise levels in the data vary and because 3D conductivity features may be encountered that may not be explained with a 1D model. Thus choosing the level of data-misfit can be difficult. Strategies such as finding a model that fits to a predefined misfit value, or a strategy of inverting the entire

line using a fixed value of the regularization parameter, can lead to poor results in locations where the noise is large and variable.

In order to help avoid these problems, a laterally parameterized methodology is followed for the inversion of AEM data.

First the best-fitting half-space models are calculated using only later times in the EM decay. These half-space values are smoothed along line and then used as reference model inputs for the layered inversions. This provides a gradually changing background conductivity, results in more consistent models from sounding to sounding, and reduces misleading conductivity modelling artifacts. The smoothed background conductivity model is also a useful exploration product when displayed as a map as it shows lateral variations in conductivity that can be a guide to deeper, underlying geology.

In an inversion we attempt to find a model that has a minimum of structure and also adequately fits the data. The balance between data misfit and model complexity is controlled by a trade-off parameter. The final value of trade-off parameter is calculated by first determining a best trade-off parameter for each sounding, and then smoothing the trade-off parameters along the line. The inversions are subsequently re-run with the smoothed estimate of the trade-off parameter used at each sounding. The resulting models are more consistent from sounding to sounding and allow for geologic features to be more easily interpreted. While some soundings will still be either over- or under-fit with the predicted data, the inconsistency is greatly reduced from when a fixed trade-off parameter is used, and generally more appropriate models are produced.

This method of determining inversion parameters by considering lateral background conductivity and data-misfit levels produces models that avoid misleading artifacts and hopefully reveal more reliable geologic information.

### 3.2.2. *Estimate of AEM Depth of Investigation.*

The meshes used in the inversion extend to considerable depth but conductivities in the lower region are determined by the reference model and not by the observations. Effectively they are beyond the depth of investigation of the survey and hence do not contain reliable information. These sections of the model should be removed from images that display final conductivity profiles. The depth of investigation depends upon the EM instrumentation and survey parameters, and also upon the conductivity structure. The depth of investigation can be estimated by carrying out multiple inversions using different backgrounds (as is done in DC resistivity inversion) but it can also be estimated using cumulative conductance rules. This does not require additional inversions. Rather, it specifies the depth of investigation to be that depth at which the cumulative conductance reaches a target value. We use that method here and the resulting models are cut-off below this depth and provide a guide to the depth to which more reliable interpretation can be made. For details refer to Appendix 6.

### 3.2.3. *Plate Modelling*

Plate modelling has been performed on over 190 individual EM anomalies in the project area. The analysis finds the parameters ( Location, orientation, extents, and conductance) of a plate that best reproduces the observed data. This analysis is appropriate when the geology is no longer 1D and flat-lying but is thinner and more vertical..



## 4. Modelling Results

### 4.1. Detailed Gravity Inversion Modelling

Local density contrast models have been produced from different local inversions. The models have been examined for consistency and merged with existing tiles for the QUEST area to construct a detailed density contrast model for the entire survey area.

The final detailed model containing all the inversion results contains over 50 million cells. Careful selection of the inversion parameters for each local inversion allowed the models to fit together very well with only limited artefacts at the model transition. Details of the inversion parameters used for the detailed inversion blocks are shown in Appendix 4. Observed and predicted data for each tile are included in the suite of digital deliverables for comparison and analysis. The density model was cut at an elevation of 8 km below sea level.

Viewing the 3D inversion output is best done with proper visualization software. However, to provide some insight about the results we show three plan-view sections. The first is the density contrast at sea-level (Figure 5); the second is the contrast at 2000 m below sea level (Figure 6), and the third 4000m below sea level (Figure 7). The shape of geologic structures can sometimes be captured by volume rendering the image and plotting iso-surfaces for a given threshold. The final image is critically dependent upon the threshold value for the iso-surface and so the interpreter will want to view the model with different thresholds. An image with an iso-surface value of  $0.05 \text{ g/cm}^3$  is shown in Figure 8. All anomalous densities with a value less than this threshold are transparent. Other visualization methods could include viewing several “stacked” sections.

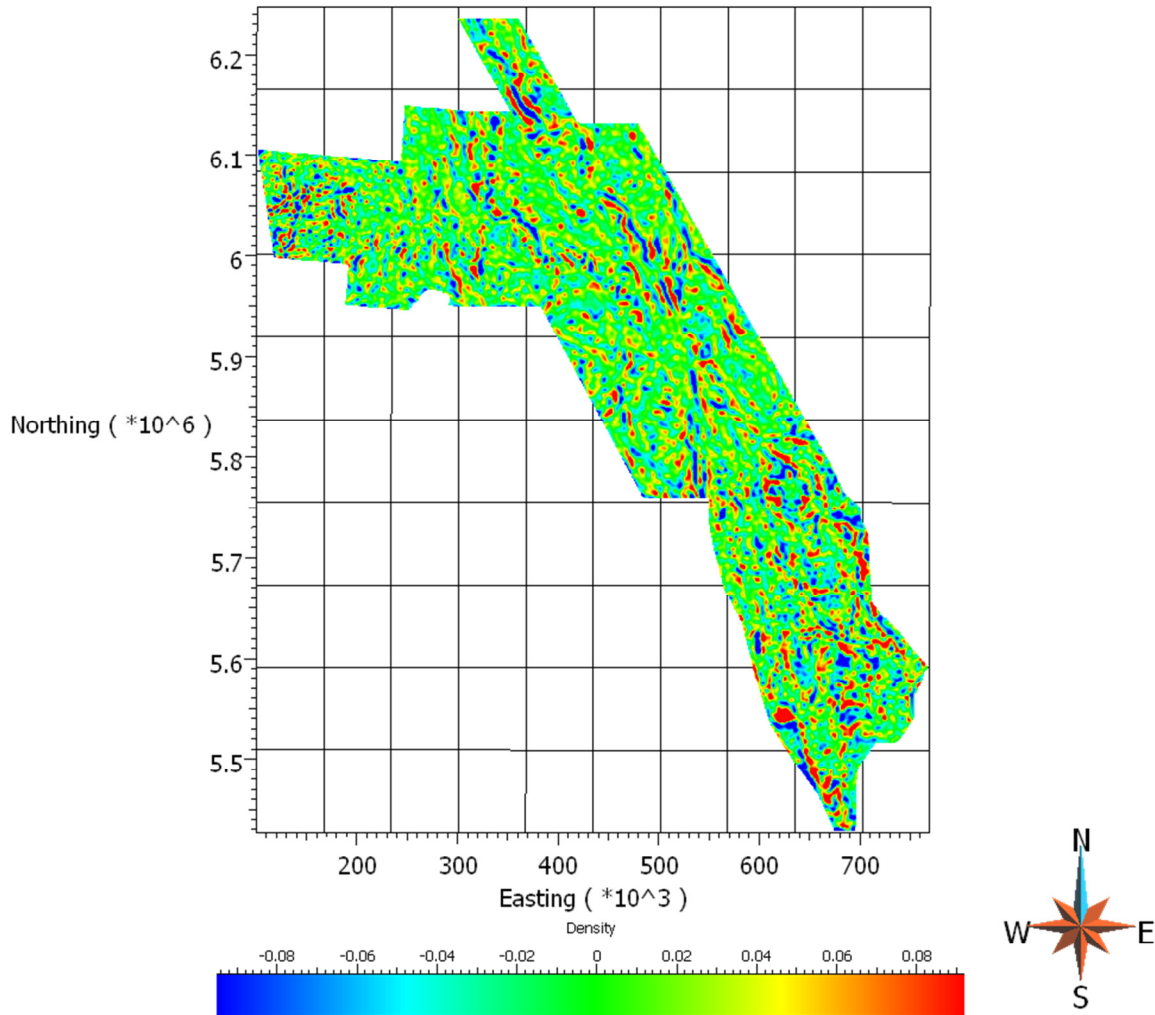


Figure 5: Plan view of the Central BC detailed density contrast model at sea level.

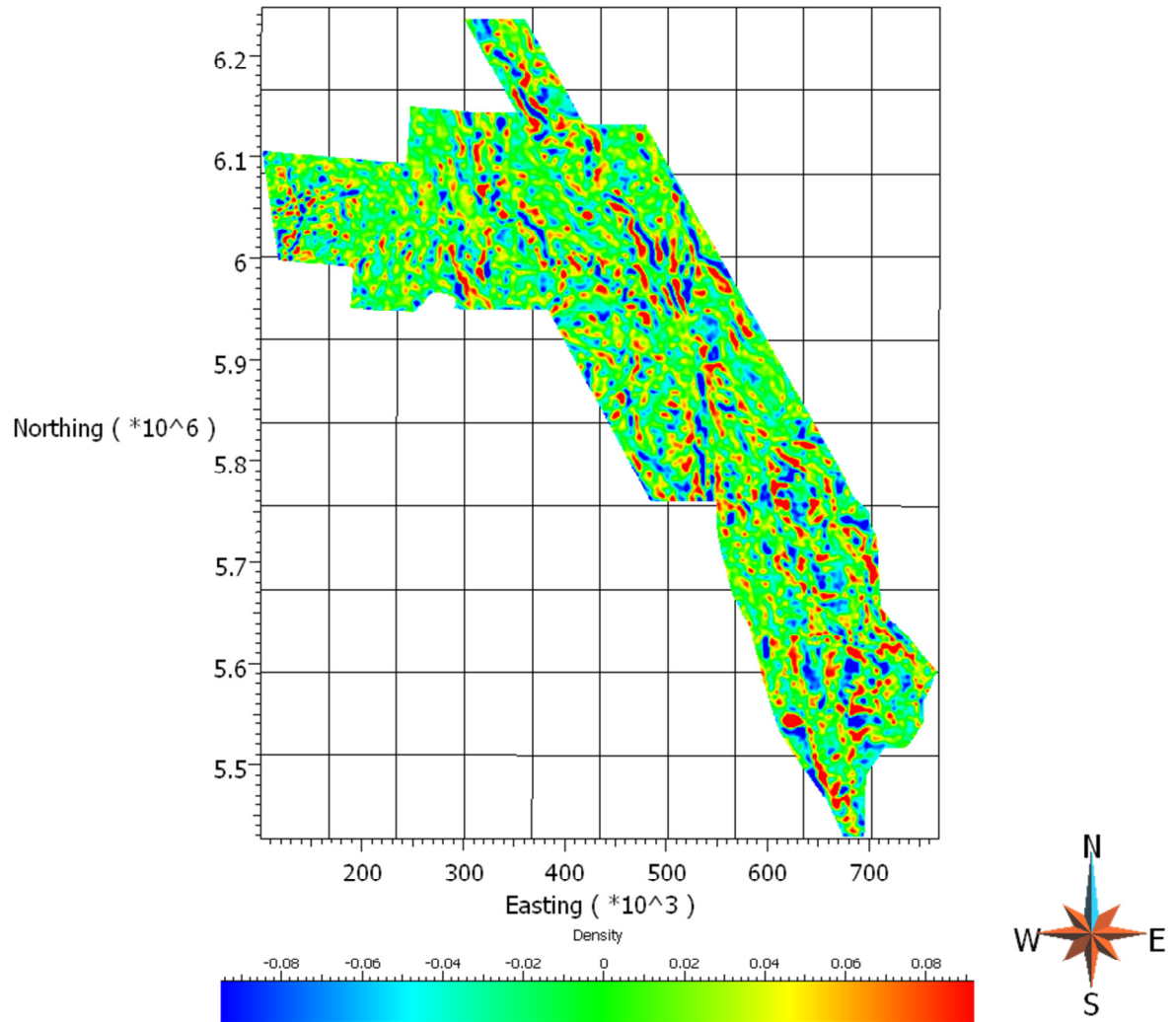


Figure 6: Plan view of the Central BC detailed density contrast model at 2000 m below sea level.

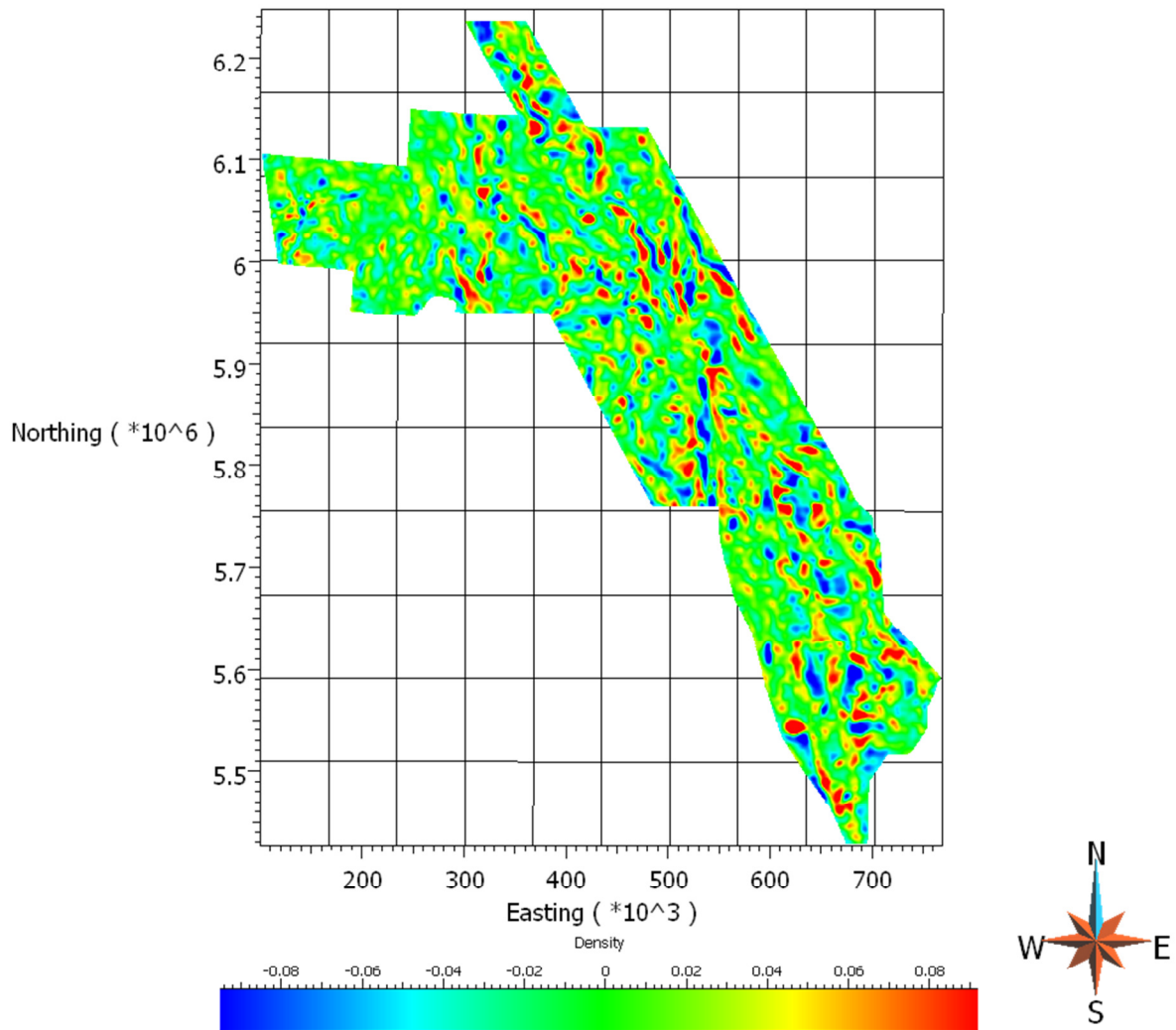
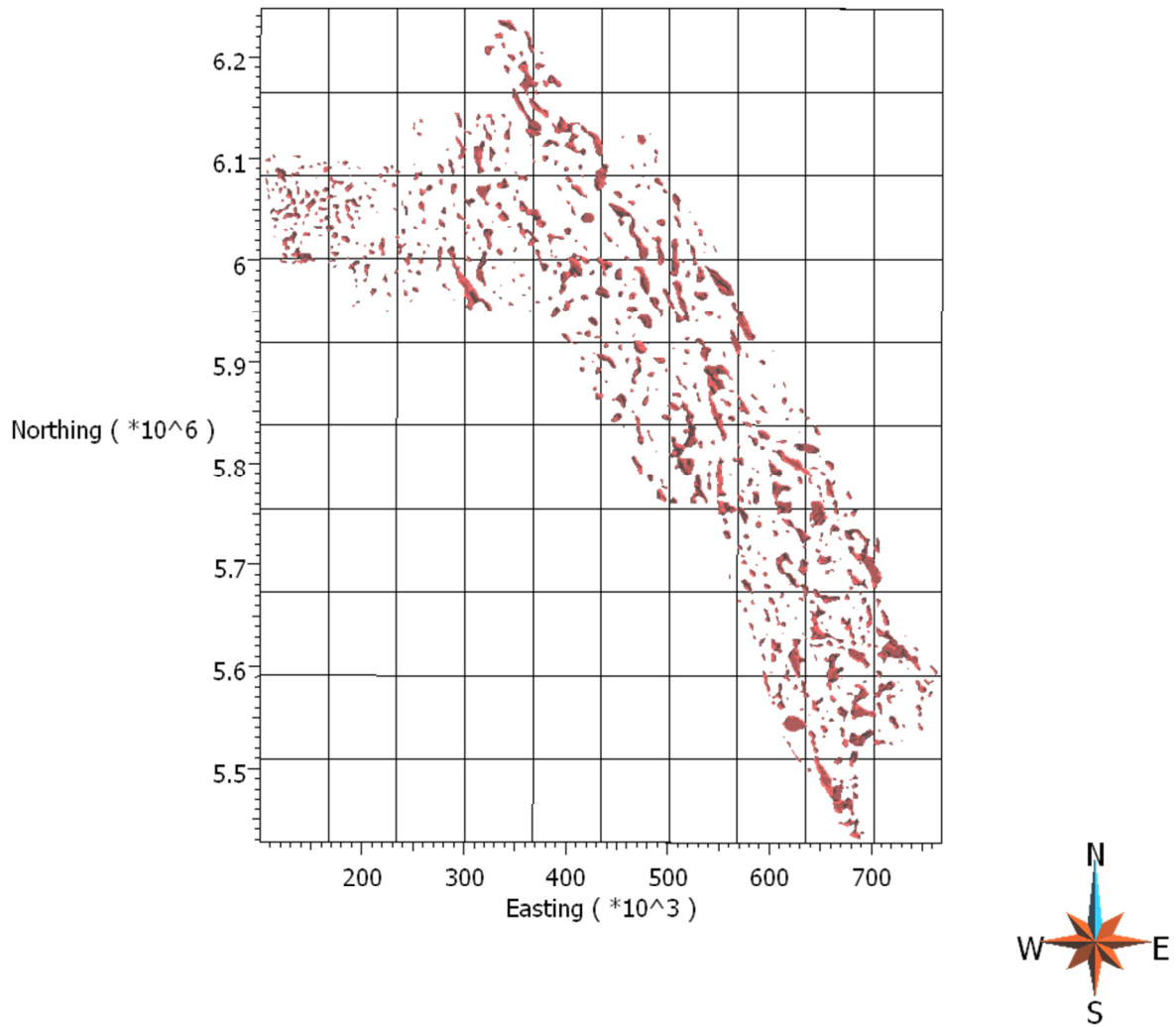


Figure 7: Plan view of the Central BC detailed density contrast model at 4000 m below sea level.

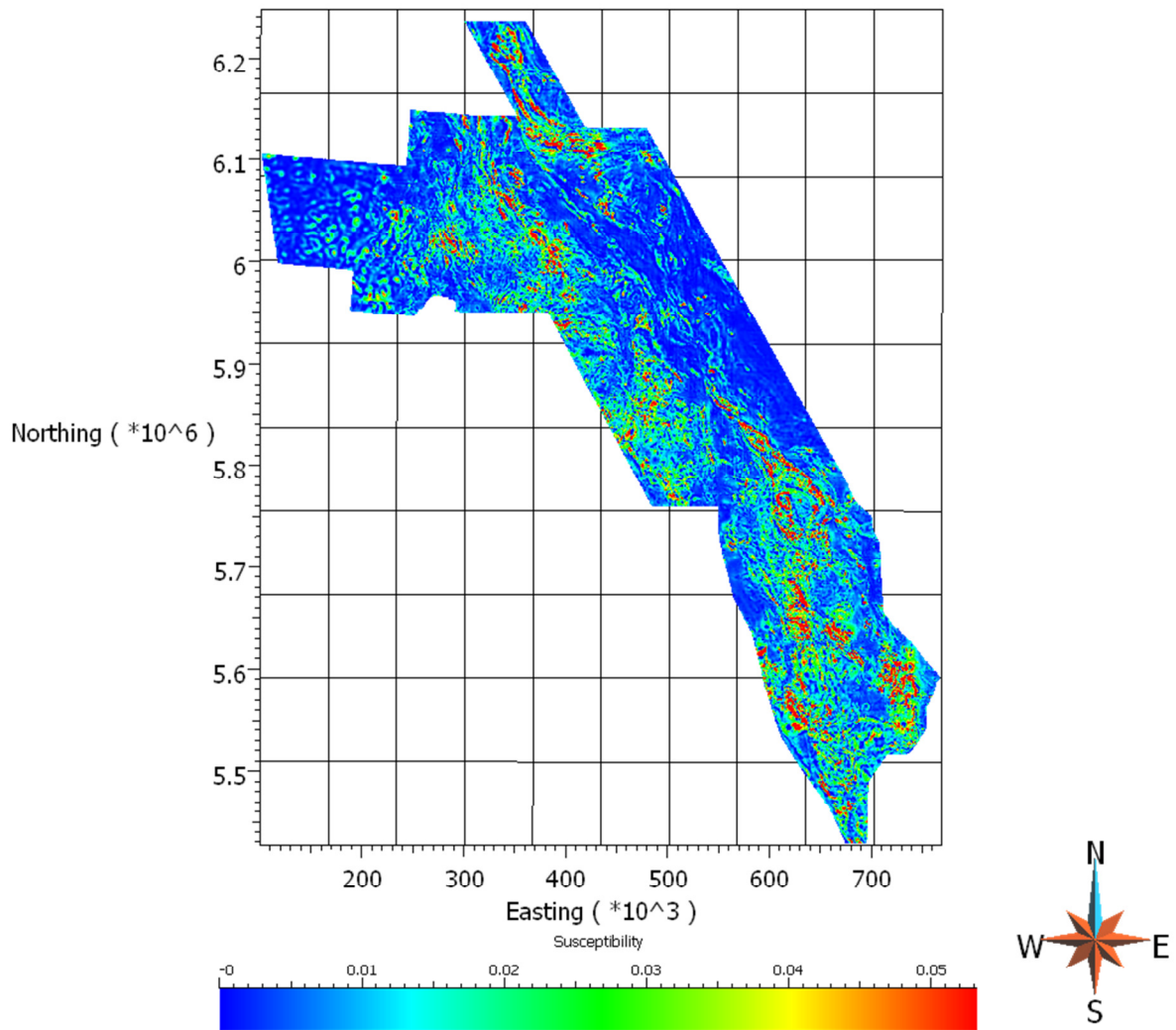


**Figure 8: Plan-view of the Central BC density contrast model showing a 3D iso-surface at 0.05 g/cm<sup>3</sup>.**

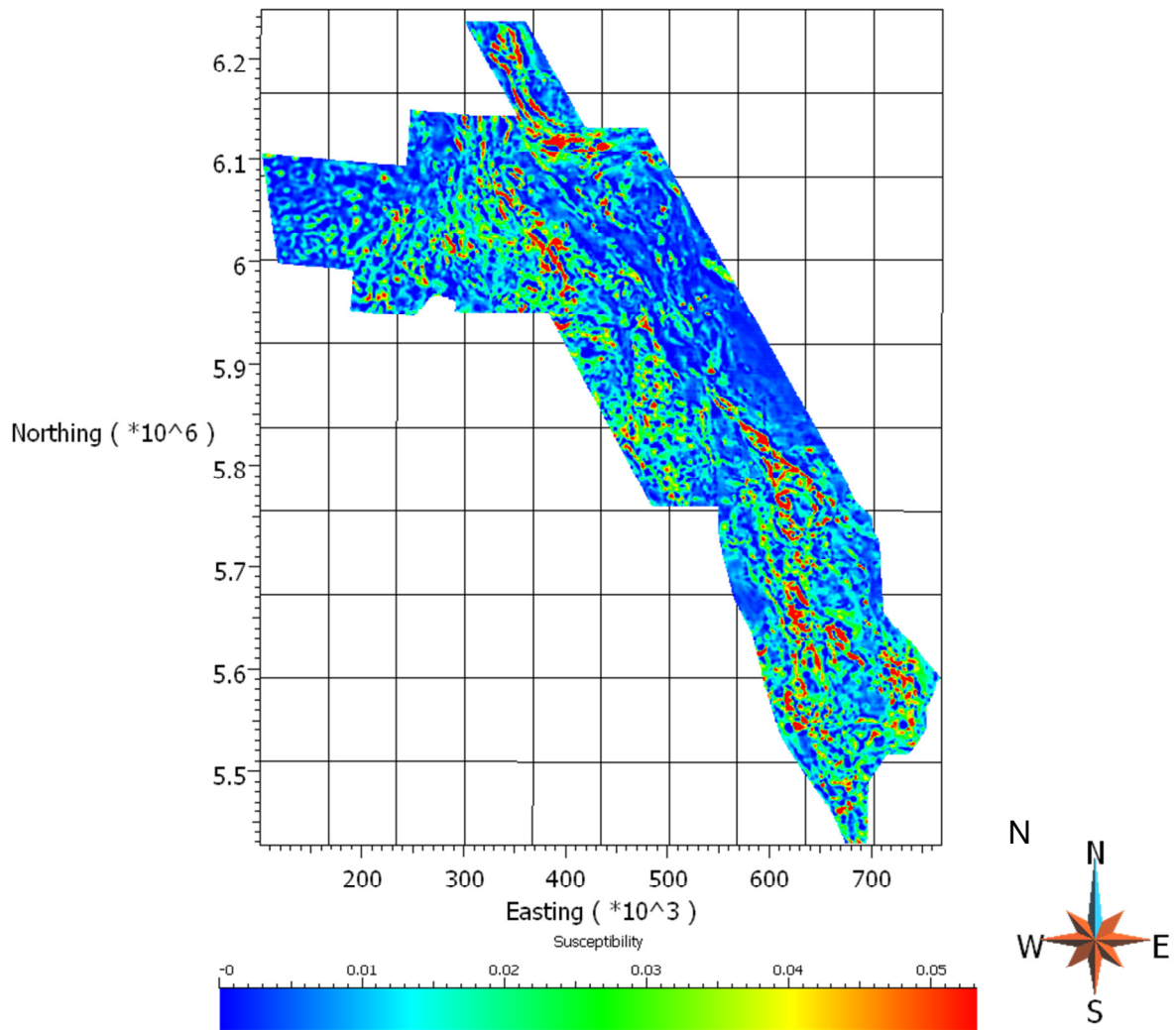
#### 4.2. Detailed Magnetic Inversion Modelling

Figure 9, Figure 10, Figure 11, and Figure 12 show 3D distributions of anomalous magnetic susceptibility. As with the density contrast model, the magnetic susceptibility model is best viewed in 3D using a variety of views with different slices, cut-off values, and colour-scales. The three plan views and the one iso-surface presented convey the main features of the magnetic susceptibility model. All magnetic susceptibility model values are in S.I.

For the merged detailed local magnetic inversions, the maximum value reaches above 0.45 S.I. This high value could be sufficient for self-demagnetization effects to be considered in some regions. Higher susceptibilities than this are probable as the model value represents the bulk volume susceptibility for the entire 500 m x 500 m x 250 m cell, and it is likely that it represents a combined effect of higher and lower susceptibilities at the sub-cell scale (a large range of sizes anywhere from the grain size up to 500 m). In addition the smooth-model inversion procedure often underestimates the property value. The models show detailed structure near the surface and gradually more smooth structure with depth which reflects the resolution of the magnetic method. Observed and predicted data for each tile are included in the suite of digital deliverables for comparison and analysis.



**Figure 9: Plan view of the Central BC detailed magnetic susceptibility model at sea level [S.I.].**



**Figure 10: Plan view of the Central BC detailed magnetic susceptibility model at 2000 m below sea level.**



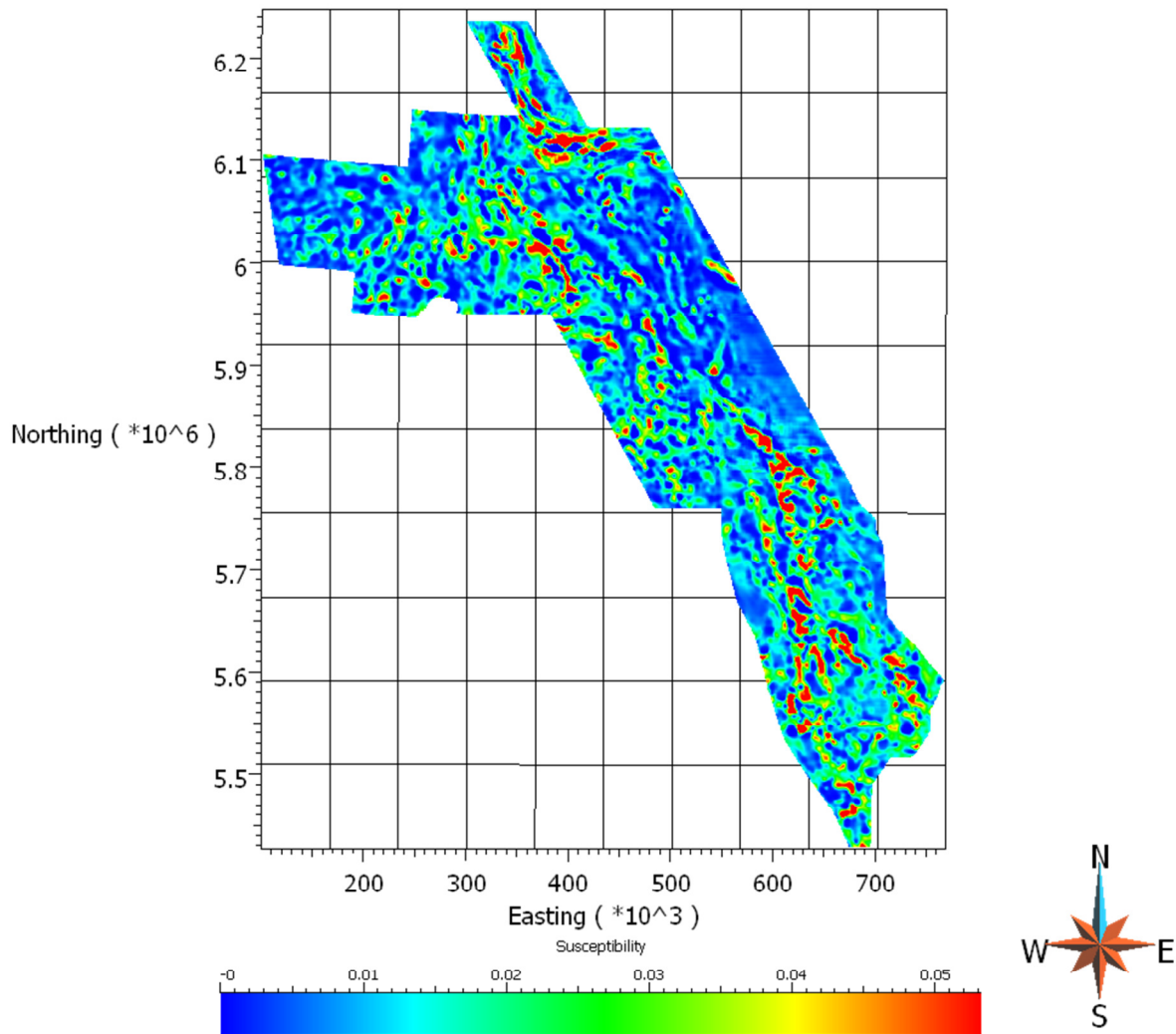
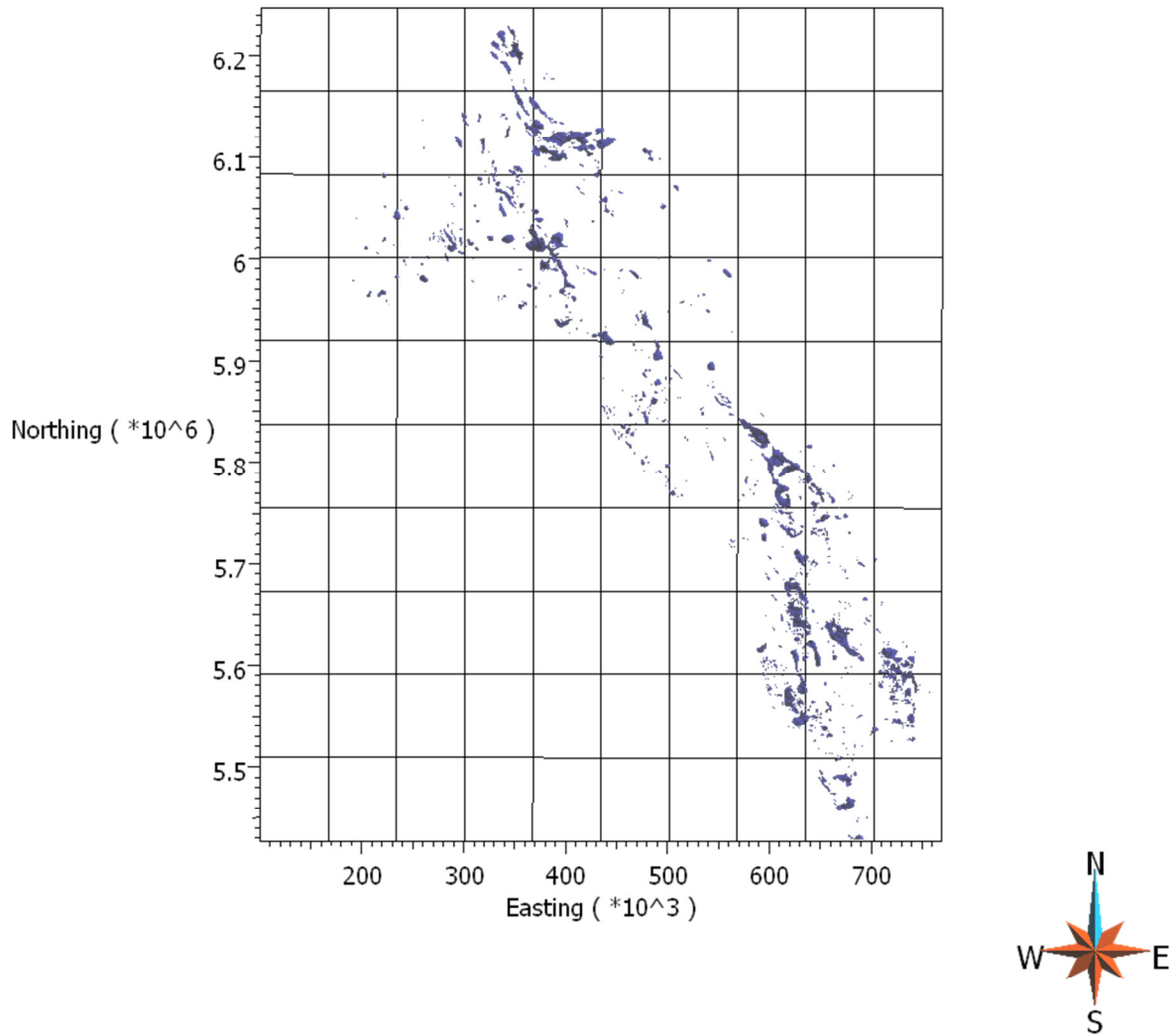


Figure 11: Plan view of the Central BC detailed magnetic susceptibility model at 4000 m below sea level.

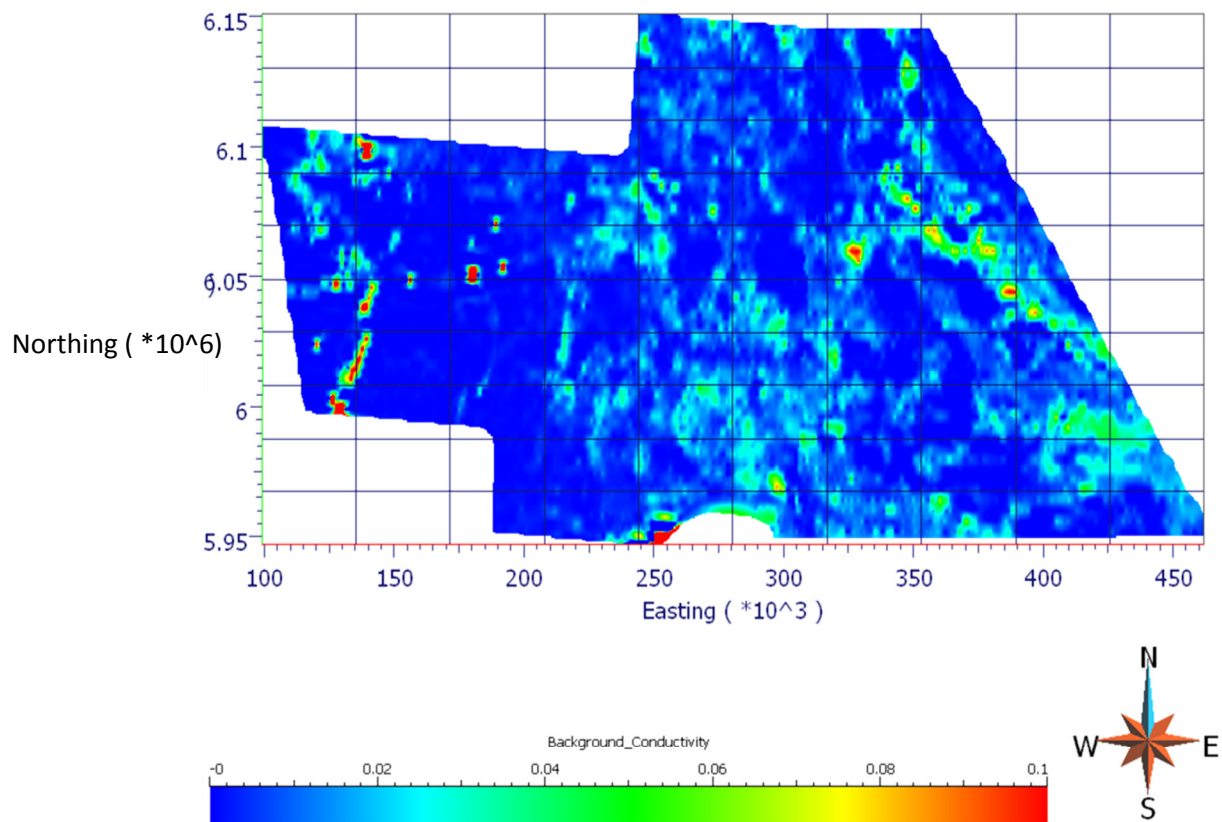


**Figure 12: Plan-view of the Central BC magnetic susceptibility model showing a 3D iso-surface at 0.05 S.I.**

### 4.3. AEM 1D Inversion Models

The background conductivity model is shown in Figure 13. The model shows the best-fitting half-space conductivity calculated from late-time data, smoothed along line. This model is used as an input reference model for the 1D EM inversions, and provides a useful guide to lateral variations in deeper geology, or at the limit of penetration of the system.

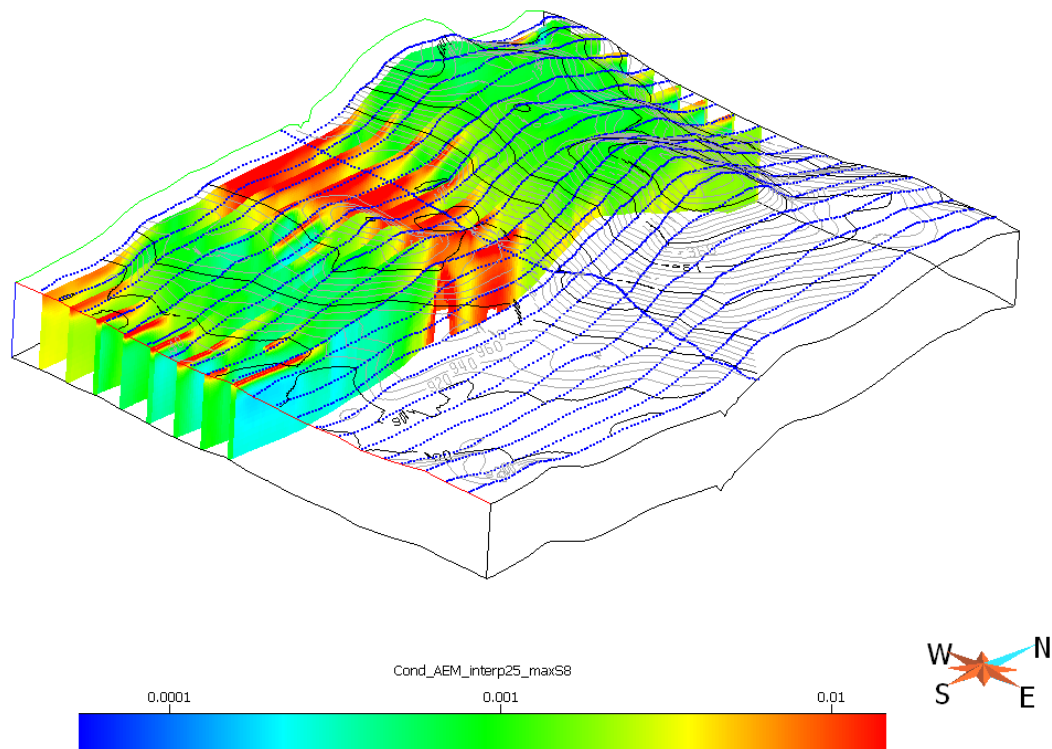
The background model is expected to show some correlation to the geology but will not show the bedrock where overlying conductive units are present.



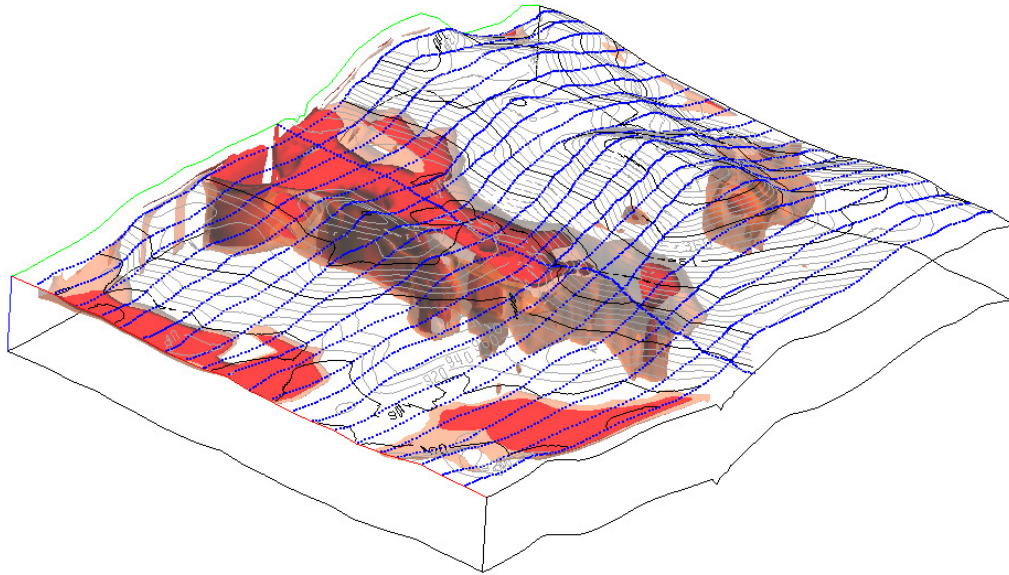
**Figure 13 Background conductivity for the QUEST West survey.**

AeroTEM dBz/dt data are inverted for a 1D (layered earth) conductivity model using the UBC-GIF EM1DTM inversion code. Stations were inverted for a 1D earth distribution of conductivity using 30 layers increasing in thickness from 2.7m to 50m with a total depth of 700m. The inversion parameters for each sounding are tabulated in Table 8 in Appendix 4.

The 1D inversion models have been interpolated in 3D in two ways. The first is a simple lateral interpolation between cells at the same depth. This produces a 3D model where the vertical axis represents depth. Another 3D conductivity model has been produced for each survey block where the model is conformable to topography. This is shown in Figure 15 as a series of North-South cross-sections that allow the conductivity model to be accessible and easily visualised.



**Figure 14 Stacked conductivity section for Huckleberry showing depth of investigation cut-off below string conductors.**

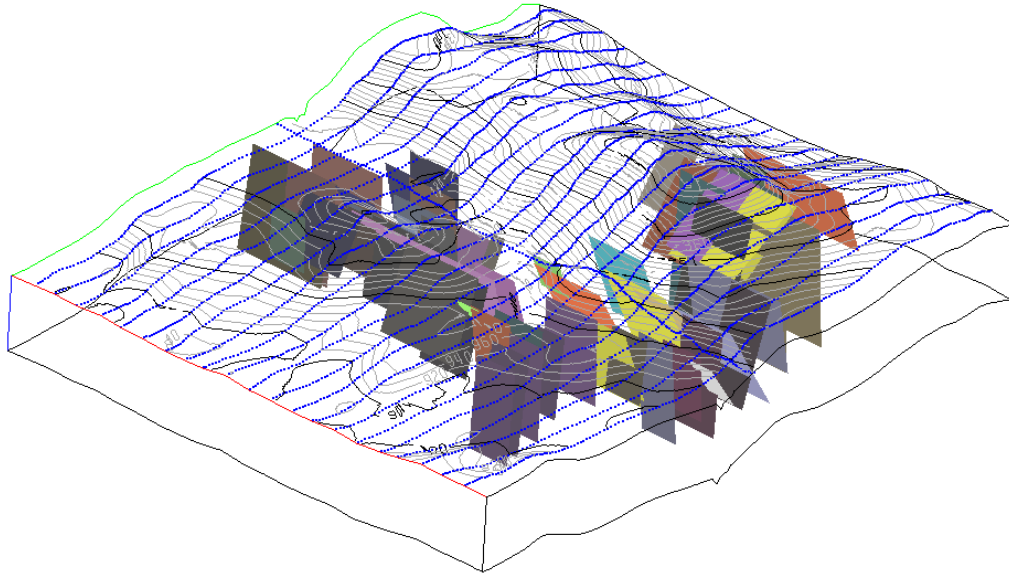


**Figure 15** Conductivity iso-surfaces for Huckleberry main conductive areas.

Figure 15 shows zones of higher conductivity and effectively delineates the east-west structure associated with the mine.

#### 4.4. AEM Plate models

Plate models have been produced for the 6 in-fill areas and provide complimentary information to the 1D conductivity inversions as compared to the iso-surfaces shown in Figure 15. Specific dips are more easily interpreted and in some places may provide a better earth model.



**Figure 16** Conductivity plate models for Huckleberry.

## 5. Deliverables

An extensive suite of digital deliverables have been prepared for distribution. The deliverables include several format types: Gocad, UBC, Geosoft, DXF, column ASCII, and PDF. The following products are provided:

- Observed and predicted data (gravity, magnetic, electromagnetic)
- 3D density contrast and magnetic susceptibility models
- Conductivity models:
  - Background Conductivity Model
  - 1D models
  - 1D models presented along line and draped under topography
  - 3D interpolated conductivity model as a function of depth below topography
  - 3D interpolated conductivity model conformable with topography.
  - Maxwell plates
- Several derivative products such as iso-surfaces and interpolated 3D models
- Gocad projects containing data and models for each survey block
- PDF3D scenes for easy visualization and communication of the results. The 3D PDF display products are produced as an output from Gocad. These can be viewed in the freely available Adobe Reader (versions 8 and higher).
- This report in PDF format.

Details of the deliverables are contained in an accompanying MS Excel spreadsheet:

Mira\_AGIC\_GeoscienceBC\_CentralBC\_Geop\_Modelling\_Appendix1\_Deliverables\_2011.xlsx

## 6. Conclusions

Detailed density contrast, magnetic susceptibility, and conductivity inversion models have been produced for the Central BC survey area. These models, and the extensive suite of associated digital deliverables, will aid visualisation, interpretation, and quantitative analysis of the data for regional exploration in the area. As well as the modelling products, the work undertaken in modelling preparation is valuable quality control of the data. This will be of benefit as exploration personnel use these geophysical data sets.

The deeper density contrast and magnetic susceptibility models can be interpreted within the context of geology in order to help define large structures and intrusives. The laterally parameterized conductivity model will be useful in determining the thickness of the overburden and the depth of investigation estimate will guide reliability of the interpretations. The background conductivity model may be useful in characterizing larger scale lateral variations of the near-surface, and the plate modelling will be useful for demonstrating the modelling of steeply-dipping features.

Although a single density contrast, magnetic susceptibility, conductivity model, and a suite of plates has been delivered, it is recognized that other models could have been chosen as appropriate model candidates. Inverse problems are non-unique and the output depends upon many factors which are difficult to quantify. The three main factors common to all inversions are: (a) how to estimate uncertainties in the data, (b) details of the model objective function and the a priori information, and (c) determining the appropriate value of the regularization parameter that balances misfit and the model objective function. Great care has been taken to winnow suspect data, remove regional fields for local inversions, estimate errors, incorporate reasonable information into reference models, and generate physical property models that fit the data well, but do not over-fit the data. In addition, because the inversion algorithms attempt to find the “simplest” (generally smooth) models that fit the data, the provided models will hopefully be representative of the larger scale features in the earth. They represent a first pass



state-of-the-art estimate of the large scale distribution of density contrast, magnetic susceptibility, and near surface conductivity in the Central BC region.

Rocks are not uniquely characterized by a single physical property. The importance of the work presented here is that there are now volumetric regions in the Central BC area that are characterized by two, and in some cases three, physical properties. These distributions can be used with 3D GIS query technology to help identify potential exploration areas (as demonstrated). In follow-up work in these local regions, inclusion of additional a priori information in the form of geologic knowledge (conceptual model, overburden thickness, drilling, outcrop lithology, etc.), petrophysical information, and further geophysics, will help guide the selection of inversion parameters and constraints so that models with enhanced resolution can be obtained. This should make exploration more successful and cost effective.

## 7. Recommendations

This suite of physical property models provides an important foundation on which to base regional exploration analysis and follow-up surveys. Several points of recommendation are made for users of these models to consider:

1. **Physical Properties:** For 3D physical property models to be used effectively for interpretation and exploration targeting, a good understanding of the exploration target physical properties will be needed which can be related to geology and geologic processes.
2. **Constraining Information:** If geologic or physical property information is made available, the models can be recreated with this information acting as a constraint on the inversion process. This would produce more reliable models that are consistent with multiple data sets. This can be performed on smaller scale regions of the model. Such information could include drill-holes, geologic maps, outcrop physical property samples, etc.
3. **Target Customization:** Integrated interpretation and 3D GIS analysis on the three physical property models can be customized to specific exploration target criteria, such that a set of model queries suitable for massive sulphide exploration would be different than queries designed for porphyry copper exploration.
4. **Survey Design for follow-up data acquisition:** Data acquired as follow-up to targeting from the physical property models, or from other data (e.g. geochemical surveys), can be collected using effective survey designs based on physical property analysis and the inversion models. This will ensure appropriate sensitivity to the exploration target is obtained. An example of this could be a DC Resistivity and IP survey being designed to target a magnetic susceptibility body at an estimated depth with known conductive overburden present to a given depth. This knowledge will allow feasibility studies to optimize the survey parameters so the goal of the survey is efficiently realised.

5. **Detailed Data acquisition:** More detailed and possibly different geophysical data can be acquired in order to define the geophysical model targets at a higher resolution. This has already been done over some deposits and prospects in the QUEST area such as the Mt. Milligan deposit where closer line-spacing infill AEM and magnetic data were collected.
6. **Integrated Modelling:** The density contrast, magnetic susceptibility, and conductivity models can be used to help constrain each other. Structures in the models that can be assumed common to both the gravity and magnetic inversions can be shared so that each model is consistent were possible. Also the 1D AEM modelling of overburden thicknesses could be used to constrain the potential field models at a smaller scale.
7. **Common Earth Model Development:** In order to continue the construction of a Common Earth Model with multiple earth properties useful for exploration targeting, more layers of information such as different geophysical data or models, geochemical data, drilling, assays, and geologic mapping and structural information can be added. This would help develop a Common Earth Model with all the important information needed to design comprehensive exploration search criteria in the project area.
8. **Additional Regional Data Coverage:** Regional airborne data coverage can be extended to cover adjacent areas, or different areas in British Columbia. This will enable the same exploration resource as demonstrated from the success of the collective QUEST projects, surveys, and data analysis.
9. **Accounting for complicated magnetization:** The magnetic inversion modelling did not account for either remanent or self-demagnetization affects. In some areas, these may be present and it will be important to understand the effect more complicated magnetization has on the data in order to avoid misleading interpretations. This should be considered if recovered magnetic susceptibility values are above 0.2 S.I. (0.4 S.I. encountered in the magnetic susceptibility model) and may become more apparent if the modelling discretization size is reduced.

## **Submittal**

The work in this report has been completed by Thi Ngoc Hai Nguyen, Amir Radjaee, and Vicki Thomson of the Mira Geoscience Advanced Geophysical Interpretation Centre under supervision by Nigel Phillips.

This report has been reviewed and approved by:

Doug Oldenburg, Principal Consultant.

14 November 2011

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## **Glossary of Useful Terms**

A brief list of commonly used terms associated with geophysical inversion methods based on those available at <http://www.eos.ubc.ca/research/ubcgif/>.

### **Anomaly**

Anomaly is a term that is used in two ways and therefore it is occasionally confusing. In general, the word means anything that is "not normal". In the context of data, we usually hope that the target or feature of interest will produce a measurable anomaly (variation in the data set) which can then be interpreted in terms of what caused it. In the context of the Earth's subsurface (or the geophysical model), a feature that can be detected or characterized may be referred to as an anomaly or an anomalous zone. For example, a subsurface void is a "density anomaly" that should produce a measurable "gravity anomaly" if a gravity survey is carried out over the void.

### **Data**

Data are measurements of a physical phenomenon such as a field, or flux, or current, or force, etc. They should be accompanied by an estimated uncertainty. To understand and work with data in inversion, it is imperative that details of the survey and instrumentation are known, viz locations/orientations of transmitters and receivers, transmitter strength, receiver gains and any processing that has been done to the data.

### **Data misfit**

Data misfit describes how close field measurements are to predicted (synthetic or calculated) data. Often we plot the real and synthetic data sets to compare for similarity. Sometimes a plot of the difference between the two data sets is generated to emphasize that variations between the two are small.

### **Discretization**

Although the earth has a continuous distribution of physical properties we simplify this with a discretization that describes the earth as a model containing a number of cells each having a



constant physical property. This model is defined on a 1D, 2D, or 3D grid or mesh. The size of the cells should reflect the resolving power of the survey. If the cells are too large important geologic features may not be adequately modeled, and also the discretization will act as a regularization in the inversion. If they are very small then many cells are required and hence the inverse problem will take longer to complete. Thus the cells should be small enough that they don't regularize the problem but their total number needs to be kept small enough so that the problem is numerically tractable.

### **Fitting the data**

Any useful model of the Earth recovered by inversion must be capable of causing the data set that was observed. This is tested by comparing the measurements to a synthetic data set generated by forward modelling based upon this recovered model. We say the "model fits the data" if it is capable of generating data that match the field measurements to within a specified degree

### **Forward modelling**

Forward modelling means simulating the data that would occur if a survey were gathered over a known model of the Earth. The reciprocal term, Inverse Modelling, describes the process of estimating a model of the earth from the data.

### **Geophysical model**

A geophysical model is a simplified concept of how one physical property is distributed within the Earth. Geophysical models are generally either an object, a halfspace, 1D (layered earth), 2D, or 3D. Note that a "model of the Earth" can mean either a geological model in which the subsurface is described in terms of rock types, structures, fluids, etc., or a geophysical model defined here defined in terms of physical properties and physical property contrasts. Often a geologist and geophysicist must work together to reconcile these two ways of understanding the Earth.



## **Geophysics**

A discipline of science which uses the tools of mathematics and physics to answer questions about the Earth.

## **Halfspace**

A volume in which half is "air" and the other half is a constant value. Geophysicists consider the earth to be a "halfspace" when the whole volume that is visible has only a constant value of the relevant physical property.

## **Interpretation**

Interpretation of geophysical data involves two steps. First the data must be interpreted in terms of a causative distribution of the relevant physical property. Then this "model" can be interpreted in terms of geology (structures, minerals, rock type alteration, etc). Geophysical interpretation may be carried out in many ways, ranging from simple data inspection to sophisticated inversion and modelling.

## **Inversion**

Inversion (or inverse modelling) is the process of mathematically estimating one or more models of subsurface physical property distributions that could explain a data set that was gathered in the field.

## **Misfit**

Misfit is a measure of how close one data set is to another. See also "Fitting the data".

## **Modelling**

Modelling usually means the process of developing models of the Earth based upon measured geophysical data. It may be as simple as recognizing that an anomaly is likely caused by a buried pipe, or it may involve sophisticated data processing and/or inversion to mathematically build a range of plausible models. Sometimes also used to refer to Forward Modelling.

## **Optimization**

A branch of mathematics related to determining the best or optimum choice from a large (possibly infinite) range of possibilities.

### **Physical properties**

Physical characteristics of the ground being investigated, such as density, electrical conductivity, and others.

### **Prior information**

Also referred to as *a priori* information. Additional information of the earth such as a known background or reference model, an expected structure or geometry, and known specific physical properties that can be assigned to cells can also be included in an inversion. These data can be used to constrain and guide the inversion. See also A Priori information.

### **Under-determined**

A problem is said to be "under-determined" when there are more unknowns than data. There are not enough equations to obtain a unique solution. Under-determined problems are inherently "non-unique".

## **Appendix 1 Project Deliverables**

Please see accompanying MS Excel file:

Mira\_AGIC\_GeoscienceBC\_CentralBC\_Geop\_Modelling\_Appendix1\_Deliverables\_2011.xls

## Appendix 2 Data and Processing Specifications

**Table 1 Sanders Gravity Survey Specifications:**

Instrument	AIRGrav
Line spacing	2000m
Line-km	27,480
Line orientation	East-West
Nominal terrain clearance	125m

**Table 2: Aeroquest Magnetic Survey Data Specification**

Inclination	74.51 degrees
Declination	20.46 degrees
Inducing Field Strength	57254 nT
Acquisition Dates	July to October 2008
Line spacing	4000m
Corrections	Diurnal, flight levelling
Nominal Flight Height	63m
Station Spacing	1.5-2.5m
Down-sampling	8 (resulting in ~16 m station spacing)
Assigned Standard Deviation	100nT

**Table 3: AeroTEM System and Data Survey Specification**

Transmitter coil diameter	10 m
Transmitter frequency	90 Hz
Peak current	455 A
Pulse width	1.71 ms
Peak dipole moment	183,131 NIA
Wave form shape	triangular
Station Spacing	1.5 – 2.5 m
Receiver – Transmitter configuration	Concentric
Coil orientation	Z-direction

The receiver decay recording scheme is shown diagrammatically in Figure 17.

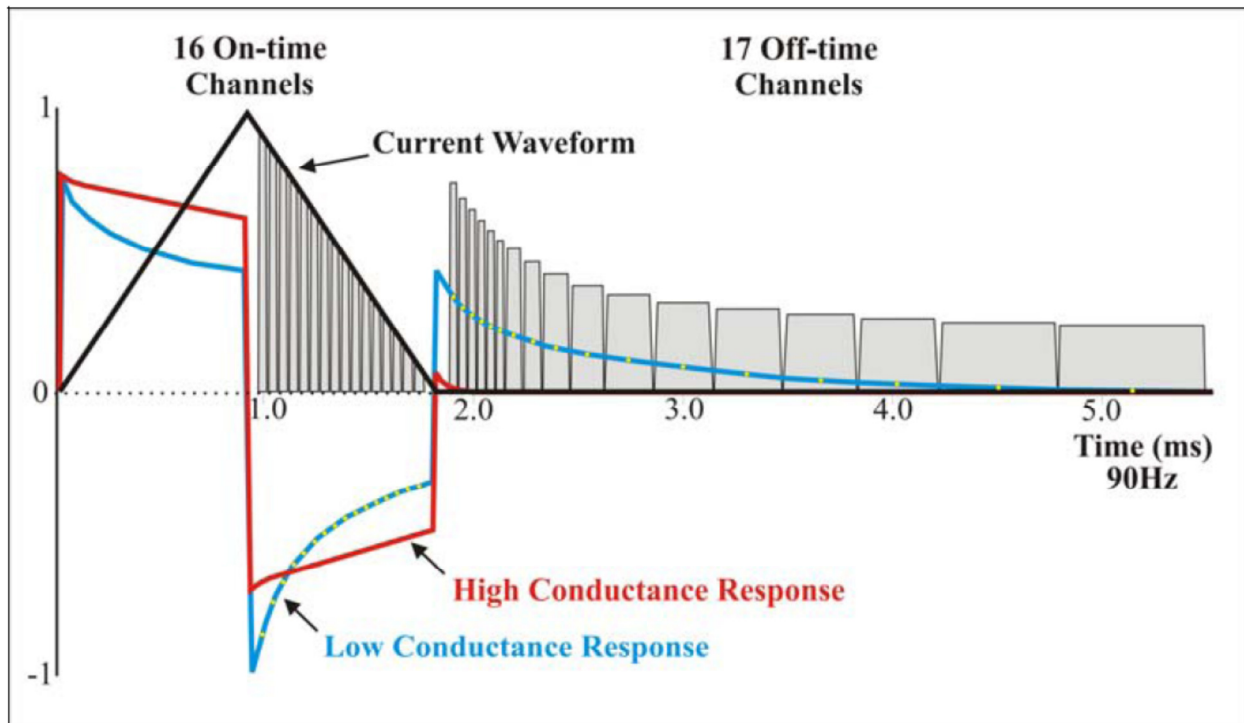


Figure 17: AeroTEM Waveform.(from GBC report 2009-6 QUEST West).

For the inversion, each datum is assigned an uncertainty that is a percentage of the datum value plus a floor. Earlier time channels generally have greater accuracy than later time channels. The table below delineates the percentages and floor values for 3 groupings of time channels.

## **Appendix 3 Modelling Software**

### **GRAV3D**

GRAV3D is a program developed by UBC-Geophysical Inversion Facility (UBC-GIF), an academic research unit within the Department of Earth and Ocean Sciences at the University of British Columbia, for carrying out forward modelling and inversion of surface, airborne, and/or borehole gravity data in three dimensions.

The program library carries out the following functions:

Forward modelling of the vertical component of the gravity response to a 3D volume of density contrast. The model is specified using a mesh of rectangular cells, each with a constant value of density contrast, and topography is included. The gravity response can be calculated anywhere within the model volume, including above the topography simulating ground or airborne surveys, and inside the ground simulating borehole surveys.

Inversion of surface, airborne, and/or borehole gravity data to generate 3D models of density contrast.

The inversion is solved as an optimization problem with the simultaneous goals of (i) minimizing an objective function on the model and (ii) generating synthetic data that match observations to within a degree of misfit consistent with the statistics of those data.

To counteract the inherent lack of information about the distance between source and measurement, the formulation incorporates a depth or distance weighting term.

By minimizing the model objective function, distributions of subsurface density contrast are found that are both close to a reference model and smooth in three dimensions. The degree to which either of these two goals dominates is controlled by the user by incorporating a priori geophysical or geological information into the inversion. Explicit prior information may also take the form of upper and lower bounds on the density contrast in any cell.

The regularization parameter (controlling relative importance of objective function and misfit terms) is determined in either of three ways, depending upon how much is known about errors in the measured data.

The large size of useful 3D inversion problems is mitigated by the use of wavelet compression. Parameters controlling the implementation of this compression are available for advanced users.

(GRAV3D Manual)



## **MAG3D**

MAG3D is a program library (version 4.0 as of August 2005) for carrying out forward modelling and inversion of surface, airborne, and/or borehole magnetic data in the presence of a three dimensional Earth. The program library carries out the following functions:

Forward modelling of the magnetic field anomaly response to a 3D volume of susceptibility contrast.

Data are assumed to be the anomalous magnetic response to buried susceptible material, not including Earth's ambient field.

The model is specified using a mesh of rectangular cells, each with a constant value of susceptibility, and topography is included.

The magnetic response can be calculated anywhere within the model volume, including above the topography, simulating ground or airborne surveys, and inside the ground simulating borehole surveys.

Assumptions: This code assumes susceptibilities are "small". This means results will be wrong when susceptibilities are high enough to cause self-demagnetization.

There is no method for incorporating remanent magnetization in this code.

Inversion of surface, airborne, and/or borehole magnetic data to generate 3D models of susceptibility contrast.

The inversion is solved as an optimization problem with the simultaneous goals of (i) minimizing an objective function on the model and (ii) generating synthetic data that match observations to within a degree of misfit consistent with the statistics of those data. To counteract the inherent lack of information about the distance between source and measurement, the formulation incorporates a depth or distance weighting term. By minimizing the model objective function, distributions of subsurface susceptibility contrast are found that are both close to a reference model and smooth in three dimensions. The degree to which either of these two goals dominates

is controlled by the user by incorporating a priori geophysical or geological information into the inversion.

Explicit prior information may also take the form of upper and lower bounds on the susceptibility contrast in any cell (as of version 4.0). The regularization parameter (controlling relative importance of objective function and misfit terms) is determined in either of three ways, depending upon how much is known about errors in the measured data.

The large size of useful 3D inversion problems is mitigated by the use of wavelet compression.

Parameters controlling the implementation of this compression are available for advanced users. (MAG3D Manual).

## **EM1DTM**

Program EM1DTM inverts time-domain electromagnetic data for one-dimensional earth models.

The observations: Off-time measurements (in the current version 1.0) are either voltage or B-field with an arbitrary current waveform flowing a horizontal transmitter loop. Receivers can be oriented in the x-, y- or z-directions, and they can be at any position relative to the center of the their transmitter loop. Transmitters are cab be any height relative to the ground surface. A “sounding” refers to all the time-decay data that correspond to what is going to be the same stack of layers at a particular horizontal location in the model. Measurement uncertainties can be provided in the same units as the observations or as as relative uncertainty in percent. Multiple soundings can be handled in a single run of the program.

Four possible inversion algorithms: 1) constant (user-supplied) trade-off parameter in the objective function being minimized; 2) the trade-off parameter chosen to achieve a user-supplied target misfit; 3) the trade-off parameter chosen using the GCV criterion; and 4) the trade-off parameter chosen using the L-curve criterion. Full flexibility of the I1 and the I2 measures of the model structure and data misfit is provided, adjustable balance between “flattest” and “smallest” components of conductivity model measure; inclusion of reference models; and inclusion of specialized weighting of the layers in the model.

The product: electrical conductivity models. The models are composed of (many) layers of uniform conductivity with fixed interfaces, and the value of the conductivity in each layer is sought in the inversion. For multiple soundings, a one-dimensional model will be produced for each sounding, and a composite two-dimensional model produced at the end of one run of the program.

(EM1DTM Manual)

## Appendix 4 Modelling Parameters

**Table 4 Regional 3D mesh parameters.**

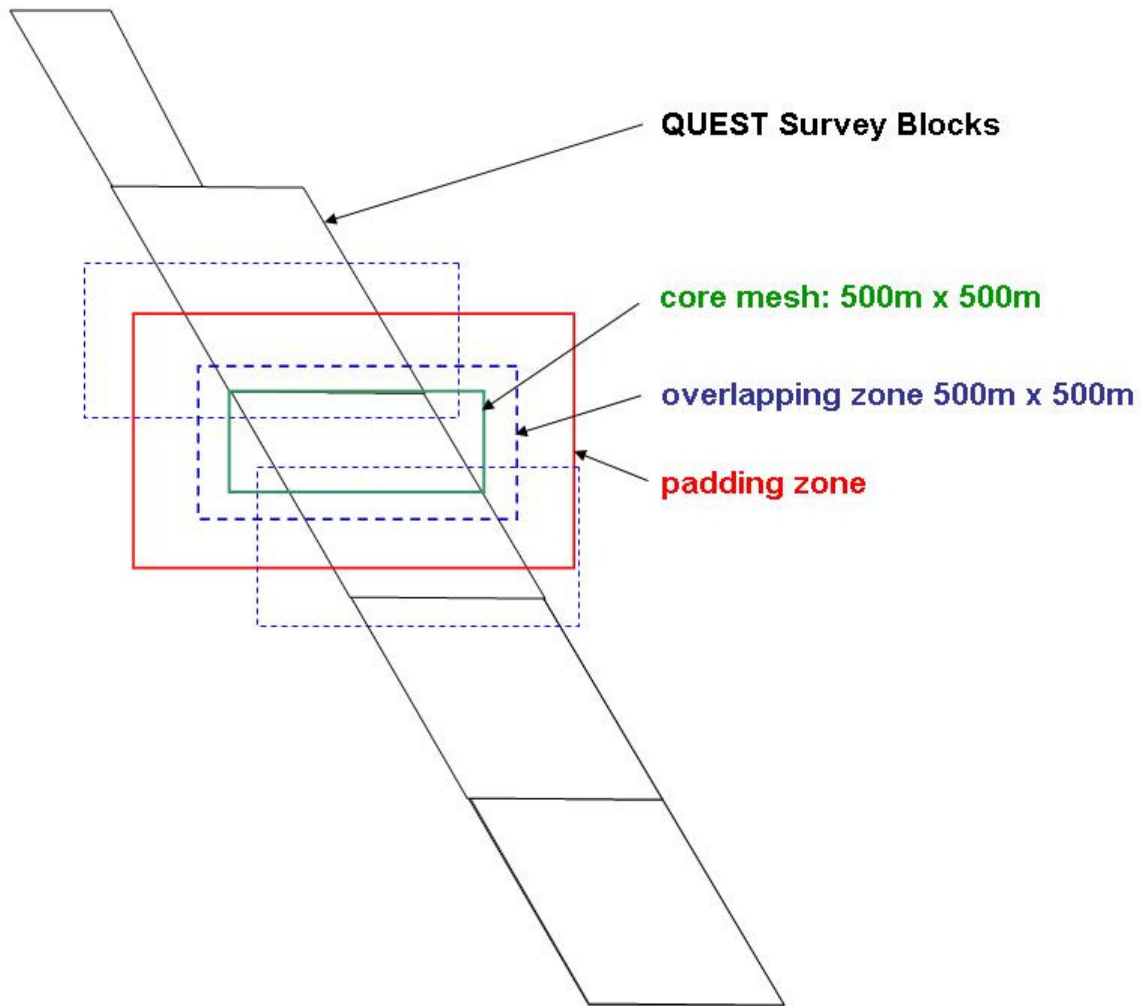
Cell size in East direction	2000 m
Cell size in North direction	2000 m
Cell size in vertical direction	250 m
Number of core cells in East direction	216
Number of core cells in North direction	253
Number of core cells in vertical direction	56
Number of padding cells in East direction	11
Number of padding cells in West direction	11
Number of padding cells in North direction	11
Number of padding cells in South direction	11
Number of padding cells in vertical direction (down)	19

**Table 5 Detailed mesh parameters (single mesh)**

Cell size in North direction	500 m
Cell size in North direction	500m
Cell size in vertical direction	250m
Number of core cells in East direction	333
Number of core cells in North direction	124
Number of core cells in vertical direction	56



Number of padding cells in East direction	11
Number of padding cells in West direction	11
Number of padding cells in North direction	11
Number of padding cells in South direction	11
Number of padding cells in vertical direction (down)	16



**Figure 18** Example potential field lateral tiling of detailed inversions showing: the core mesh for each inversion, the overlapping zone used for the regional separation and used for the detailed inversion and merging afterwards, and the padding zone (taken from QUEST example).

**Table 6 Detailed Gravity Inversion Parameters (for parameters that were consistent between tiles)**

Sensitivity wavelet relative threshold	0.002
Convergence mode	Fixed target misfit
Global Density contrast Bounds (g/cm <sup>3</sup> )	-2, 2 (min, max)
Length scales (Le, Ln, Lz)	1.500E+03, 1.500E+03, 1.000E+03

**Table 7: Magnetic Inversion Modelling Specifications**

<b>Inversion Modelling Parameters</b>	<b>Inversion Modelling Parameter Value</b>
Convergence Criteria	Chi-factor = 1
Length scales (Le, Ln, Lz)	1.500E+03, 1.500E+03, 1.000E+03
Number of data inverted	41168 (example for one tile)
Global Susceptibility Bounds	0, 1 S.I. (min, max)

**Table 8 EM1DTM inversion input file parameters for each sounding**

Root name	result
Observation file	obs.dat
Starting conductivity model	From smoothed half-space inversion of late-time data
Reference conductivity model	From smoothed half-space inversion of late-time data
Reference conductivity model (flat)	From smoothed half-space inversion of late-time data
Weights	None

Objective Function Parameters (hc, eps, ees, epz, eez, acs, acz)	1000 2 0.0001 2 0.0001 0.001 1
Inversion Type	Fixed beta
Trade-off parameter decrease	0.5
Maximum number of iterations	15
Convergence Test	0.0001
Hankel kernel evaluations	100
Fourier kernel evaluations	100
Level of output written to file	1



## **Appendix 5 Magnetization**

### **Linear Magnetization**

Local magnetic anomalies in the data are due to the magnetic field produced by magnetically susceptible material beneath the surface that has been magnetized by the earth's ambient magnetic field. The majority of the response comes from shallow material due to the fast fall-off nature of the magnetic field. For low susceptibilities ( $< \sim 0.2$  SI) the strength of the magnetization vector, and resulting field, is a linear relationship between the earth's field flux intensity and susceptibility. This makes interpretation relatively intuitive and modelling a less complex process.

### **Self-Demagnetization**

For high magnetic susceptibilities ( $> \sim 0.2$  S.I) the relationship between the strength of magnetization and susceptibility is non-linear. This non-linear relationship is the cause of the phenomena known as self-demagnetization where a component of the magnetization opposes the earth's field. The effect of self-demagnetization, which aligns the magnetization vector with the long-axis of the magnetic body, is to reduce the amplitude of the anomaly and change the anomaly location and shape, thus making traditional interpretation unreliable (Wallace, 2007). A typical result of considering only linear magnetization in modelling routines when non-linear magnetization is present is for the resulting dip of a magnetic body to be too shallow.

### **Remanent Magnetization**

Remanent magnetization (or remanence) is a permanent magnetization that can be obtained by ferromagnetic material through several phenomena including thermo-, chemical and detrital remanence. Often, the remanence obtained in the past becomes oriented in a direction different from the Earth's field today; this can occur through movement of the Earth's magnetic poles or

through tilting of the stratigraphic units containing the permanently magnetized material. Hence, the induced and remanent components can be oriented in different directions.

Typical magnetic inversion routines assume no remanent component exists, employ a magnetization direction aligned with the current earth's inducing field, and erroneous results can be obtained from this incorrect assumption. (Lelievre et al., 2006). A typical result of not considering remanent magnetization is similar to that of the self-demagnetization effect, where the direction of inducing magnetization is incorrect and resulting dips of magnetic bodies can be incorrect or a diagnostic cone of zero magnetic susceptibility can propagate from the surface down through the model.

## **Appendix 6 Estimate of AEM Depth of Penetration**

The effective depth of penetration of a geophysical survey will depend on the source of the anomalous signal and the configuration of the receiver. A commonly used technique for estimating the depth of investigation in inversion modelling of DC resistivity and IP data is to consider at what depth the recovered model returns to a reference model (Oldenburg and Li, 1999). The depth at which the model returns to the reference model is deemed the depth at which the observed data will no longer influence the model parameters, and hence reflects the maximum depth of investigation. A comparison of recovered models with different reference models can be used for determining a depth of investigation index.

The approach of using different reference models has been applied to 1D AEM inversions but this at least doubles the number of individual inversions required. An alternative method of estimating the depth of investigation has been applied where the cumulative conductance is calculated from the uppermost discretized layer downwards. (This is a much faster calculation which does not involve additional inversions.) The depth at which a given cut-off conductance is reached will provide an alternate estimate of the depth of penetration. Tests can be conducted on a single line of inversions in order to calibrate the cut-off conductance value with the reference model depth of investigation method described above. It should be noted that both methods are subjective as either a cumulative conductance cut-off or a depth of investigation index value has to be chosen.

The resulting models cut-off below this depth of investigation show reasonable and practical interpretation of the inversion models where resistive regions have deeper penetration (as there is nothing to hinder the rapid propagation of the electromagnetic fields), and conductive zones effectively shield the underlying earth and show shallow investigation.

The depth of investigation method presented here is purely an estimate of the depth to which the inversions models might be considered more reliable. While they seem to be a reasonable guide, they are not meant to reflect absolute penetration of the acquisition system. 1D AEM inversion conductivity models are provided with and without this cut-off applied.

Guidance on the application of this approach was provided by Peter Kowalczyk from Geoscience BC.